

# Power and Limitations of Graph Neural Networks

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Seminar for Deep Neural Networks

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# Content

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1. Graph Neural Networks
2. Weisfeiler Lehman Isomorphism Test
3. GNNs with port numbering
4. Distributed computing
5. Communication capacity
6. Oversquashing
7. Conclusion

# Graph Neural Networks

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# Graph Neural Networks

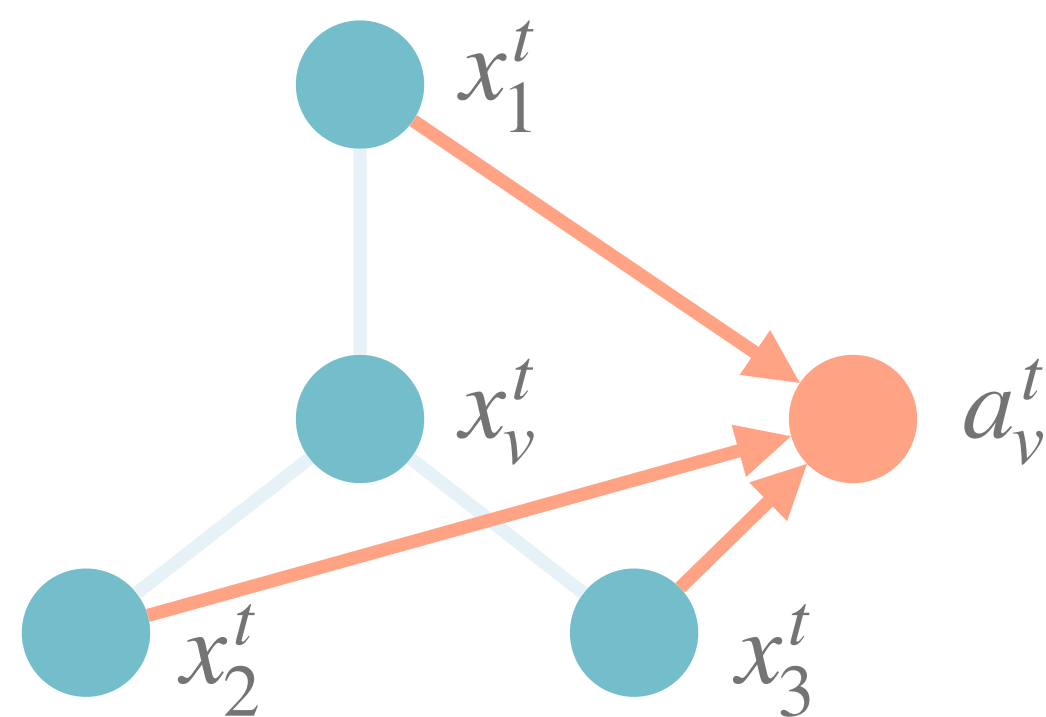
## Basic definition

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- Input: Graph  $G = (V, E)$  with graph labels  $x_v$  for each vertex  $v \in V$
- Each layer consists of two steps<sup>[1]</sup>

1) Aggregate features of neighboring vertices

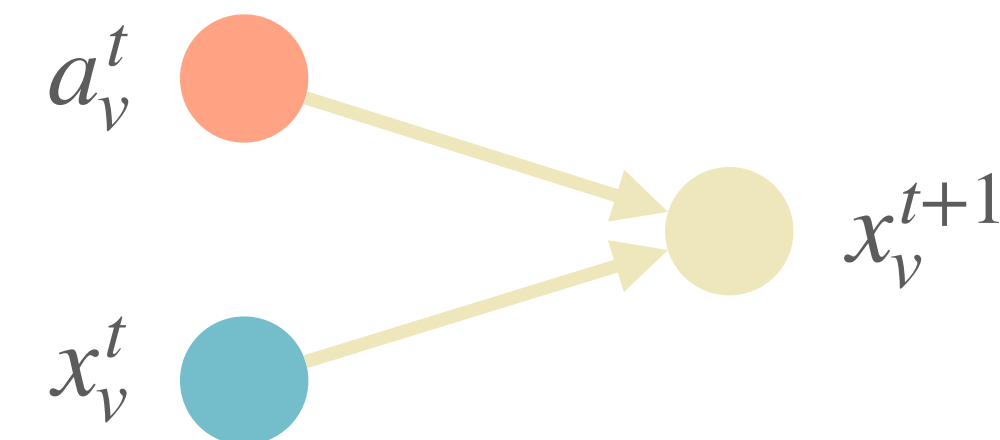
$$a_v^t = \text{AGGREGATE}^t(\{x_u^t \mid u \in \mathcal{N}(v)\})$$



Examples: Sum, Mean, Max, MLPs

2) Combine aggregate with current vertex label

$$x_v^{t+1} = \text{COMBINE}^t(x_v^t, a_v^t)$$



Examples: Concatenation + Linear Mapping

# Graph Neural Networks

Layer function

- We can combine the aggregate and combine functions to a single layer function  $f_\theta$

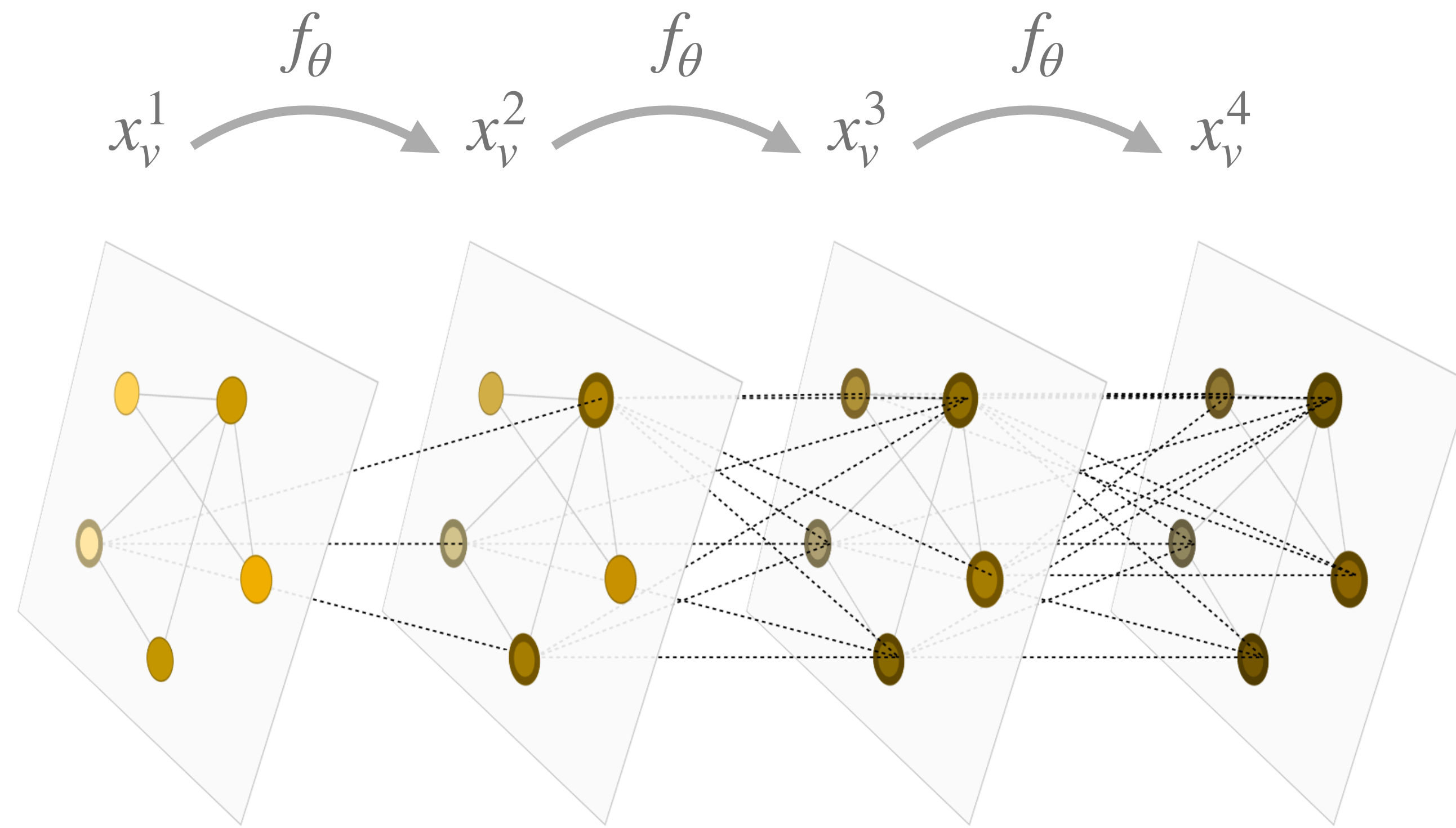
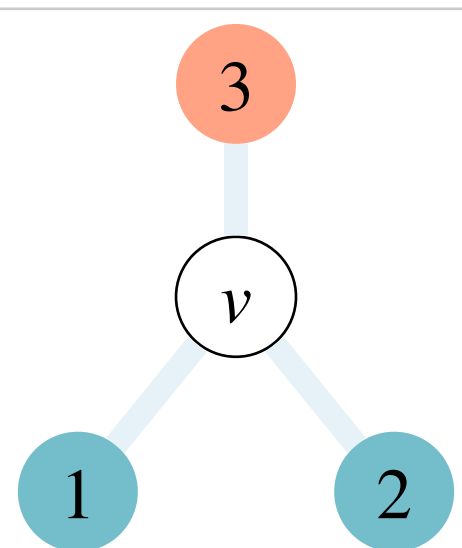
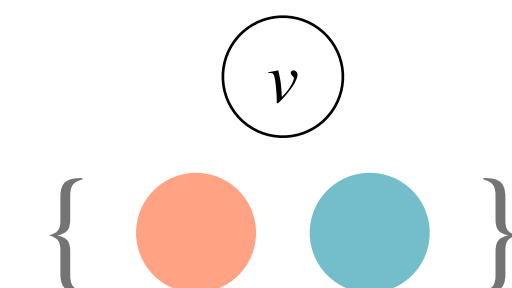
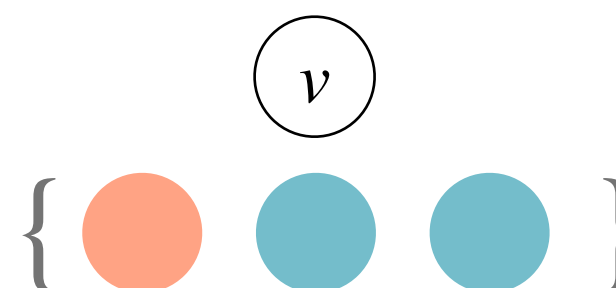
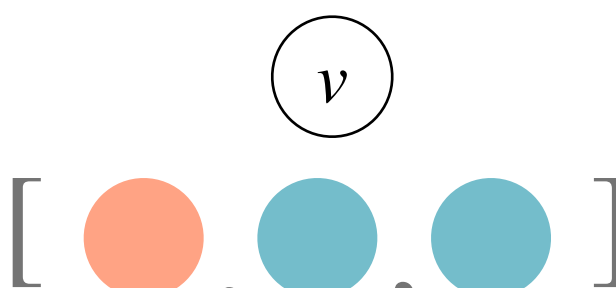
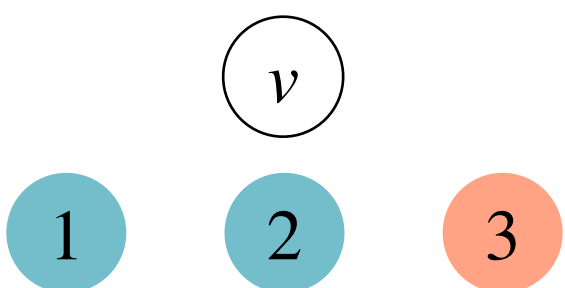


Figure 1: Propagation of information in a graph neural network

# Graph Neural Networks

## Classification

- Depending on layer function we can distinguish between different GNN classes with different computational complexity<sup>[2]</sup>

Model	Set broadcasting GNNs	Multiset broadcasting GNNs	Vector-vector consistent GNNs	GNNs with access to unique vertex IDs
 <p>Input</p>	 <p>Set</p>	 <p>Multiset</p>	 <p>Multiset and port numbering</p>	 <p>Unique vertex IDs</p>

# Graph Neural Networks

## Readout function

- Often, we are interested in graph level classification/regression tasks
- GNNs can be extended through a *READOUT* function that combines features from all nodes

$$x_G = \text{READOUT}(\{x_v^T \mid v \in V\})$$

(where  $T$  denotes the index of the last layer)

- Should be permutation invariant
- Examples: Summation, Mean/Max-Pooling

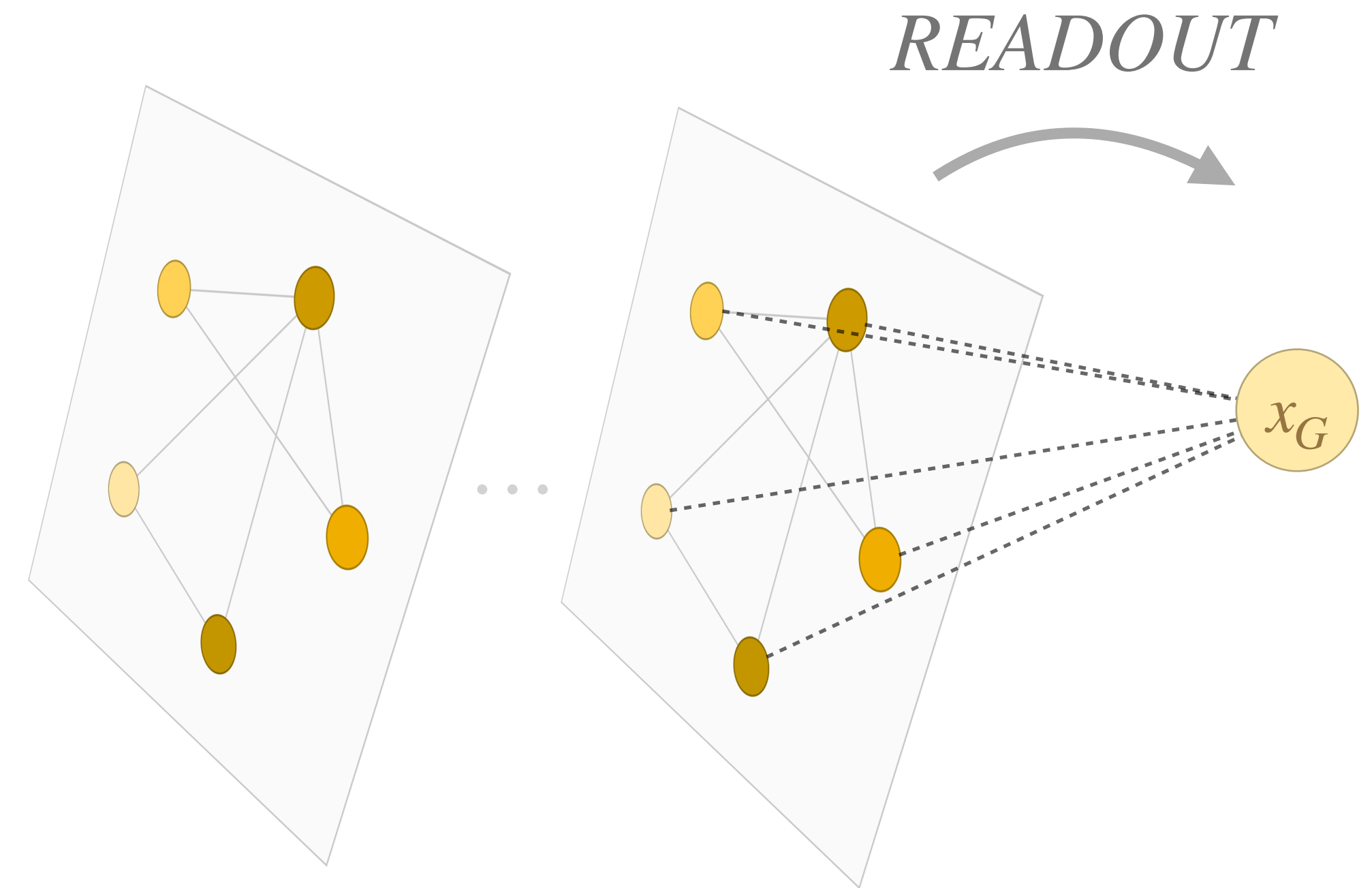


Figure 2: *READOUT* function in a graph neural network

# Graph Neural Networks

## Depth and Width

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### Definition 1

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The depth  $d$  of a Graph Neural Networks is equal to its number of layers.

### Definition 2

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The width  $w$  of a Graph Neural Network is equal to the largest dimension of  $x_v^t$  for any vertex  $v$  and layer  $t$

$$w = \max_{v \in V} \max_{t \in \{0, \dots, d\}} \dim(x_v^t).$$

- The depth and width of a GNN play a crucial role in its computational power



# The Weisfeiler Leman Isomorphism Test

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# Graph isomorphism

## Definition

Two labeled graphs  $G = (V, E, X)$  and  $G' = (V', E', X')$  are isomorphic if there exists a bijection  $f: V \rightarrow V'$ , such that

i)  $(f(u), f(v)) \in E'$  for all  $(u, v) \in E$   
 $(f^{-1}(u'), f^{-1}(v')) \in E$  for all  $(u', v') \in E'$

ii)  $x'_{f(v)} = x_v$  for all  $v \in V$

- In unlabelled case we can omit labels, or set  $x_v = 0$  for all vertices  $v \in V$

- Unknown whether it is solvable in polynomial time

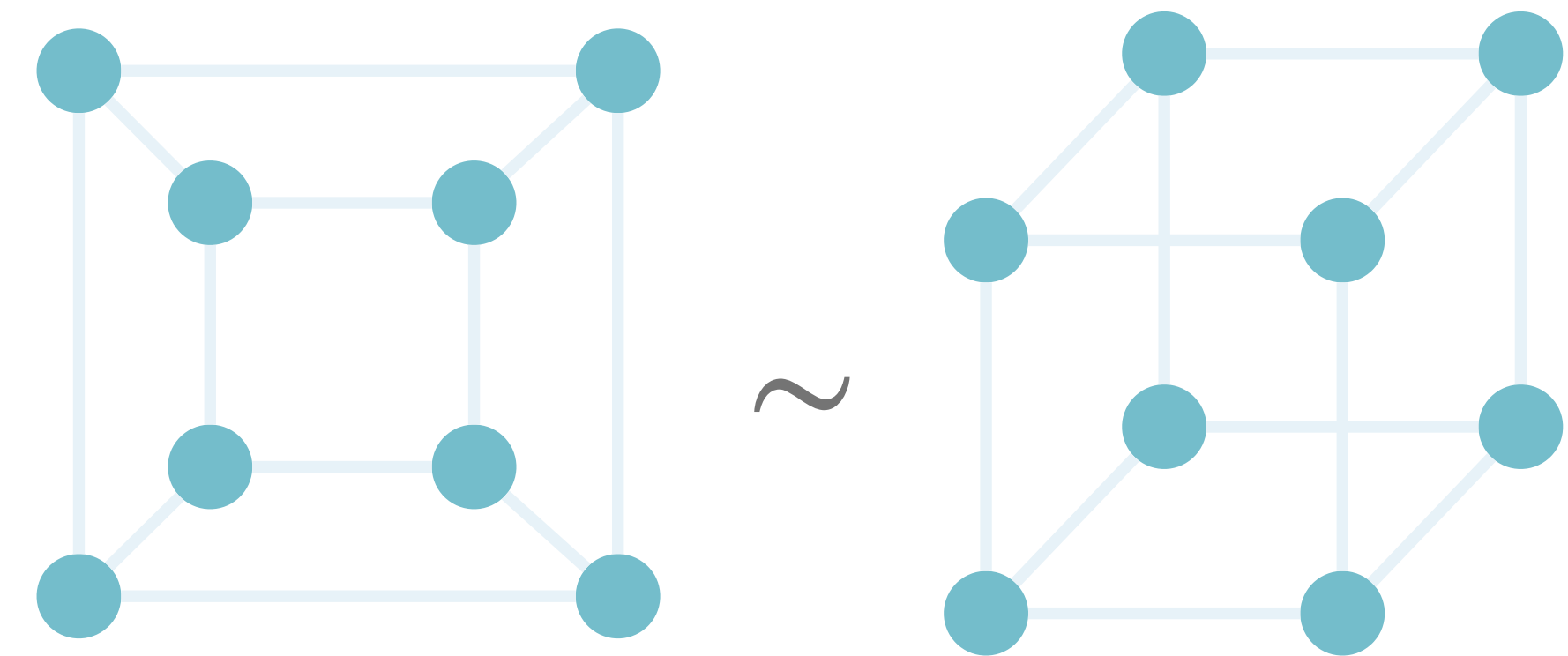


Figure 3: Two (unlabelled) isomorphic graphs

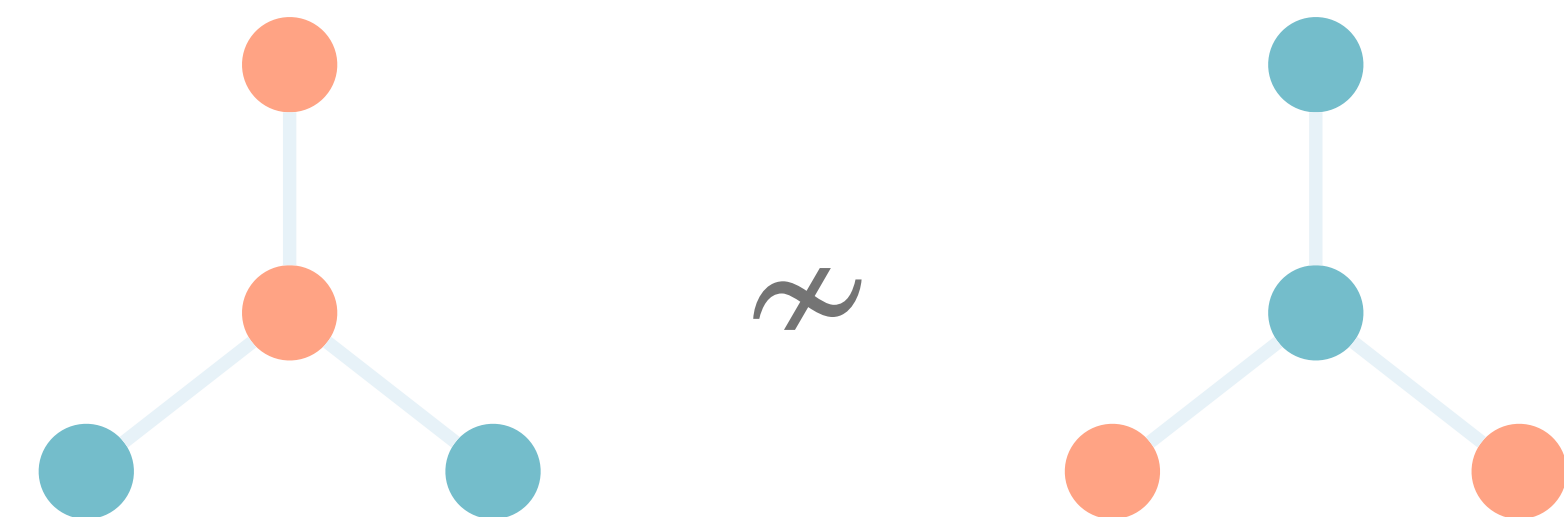


Figure 4: Two (labelled) non-isomorphic graphs

# WL Isomorphism Test

## Overview

- Algorithm for solving the graph isomorphism problem
- Idea: Iteratively reduce graphs to canonical forms that coincide if graphs are isomorphic
- If canonical forms differ, graphs are non-isomorphic
- In each step  $t$ , assign to every node  $i$  a label  $x_i^t$

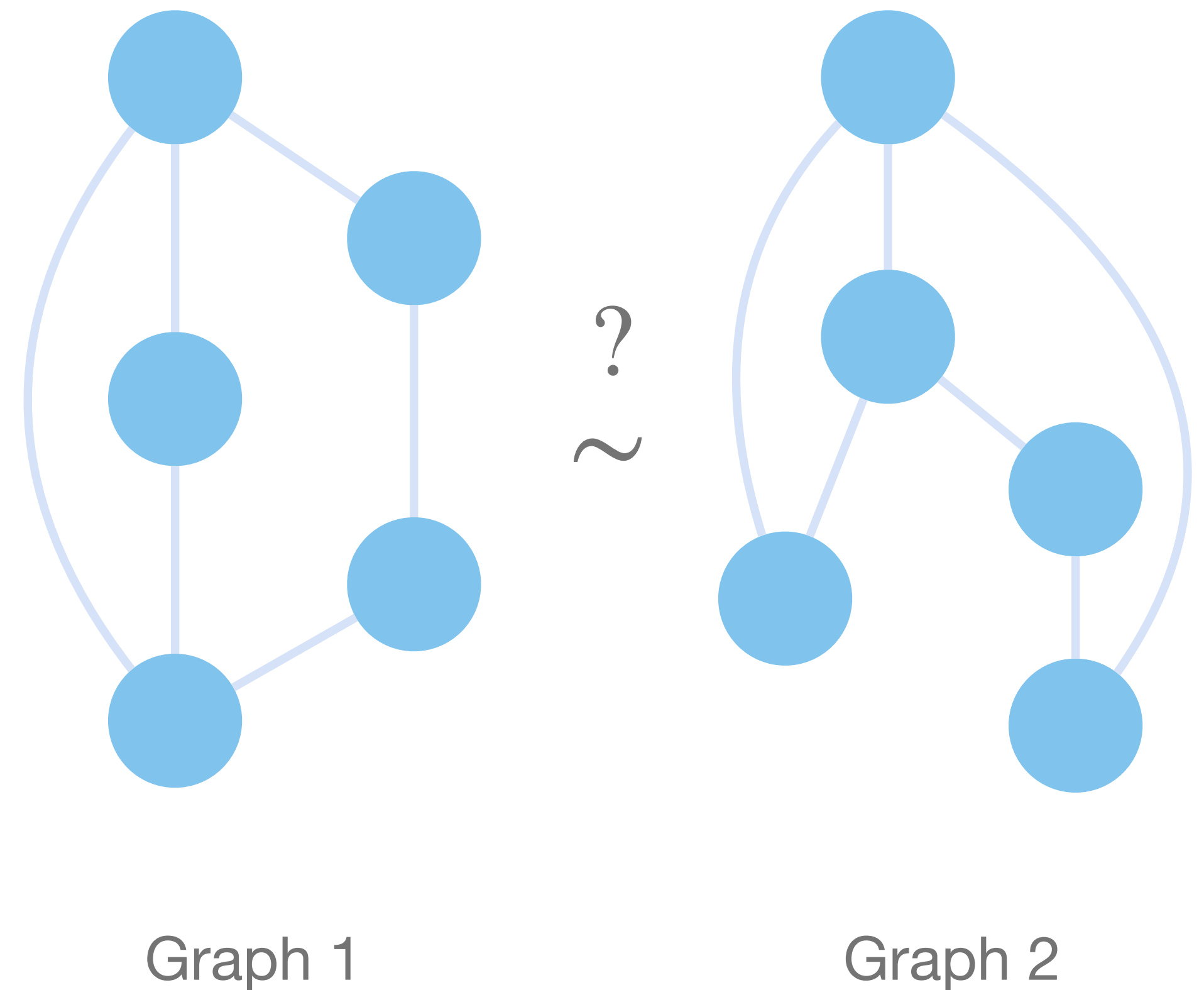


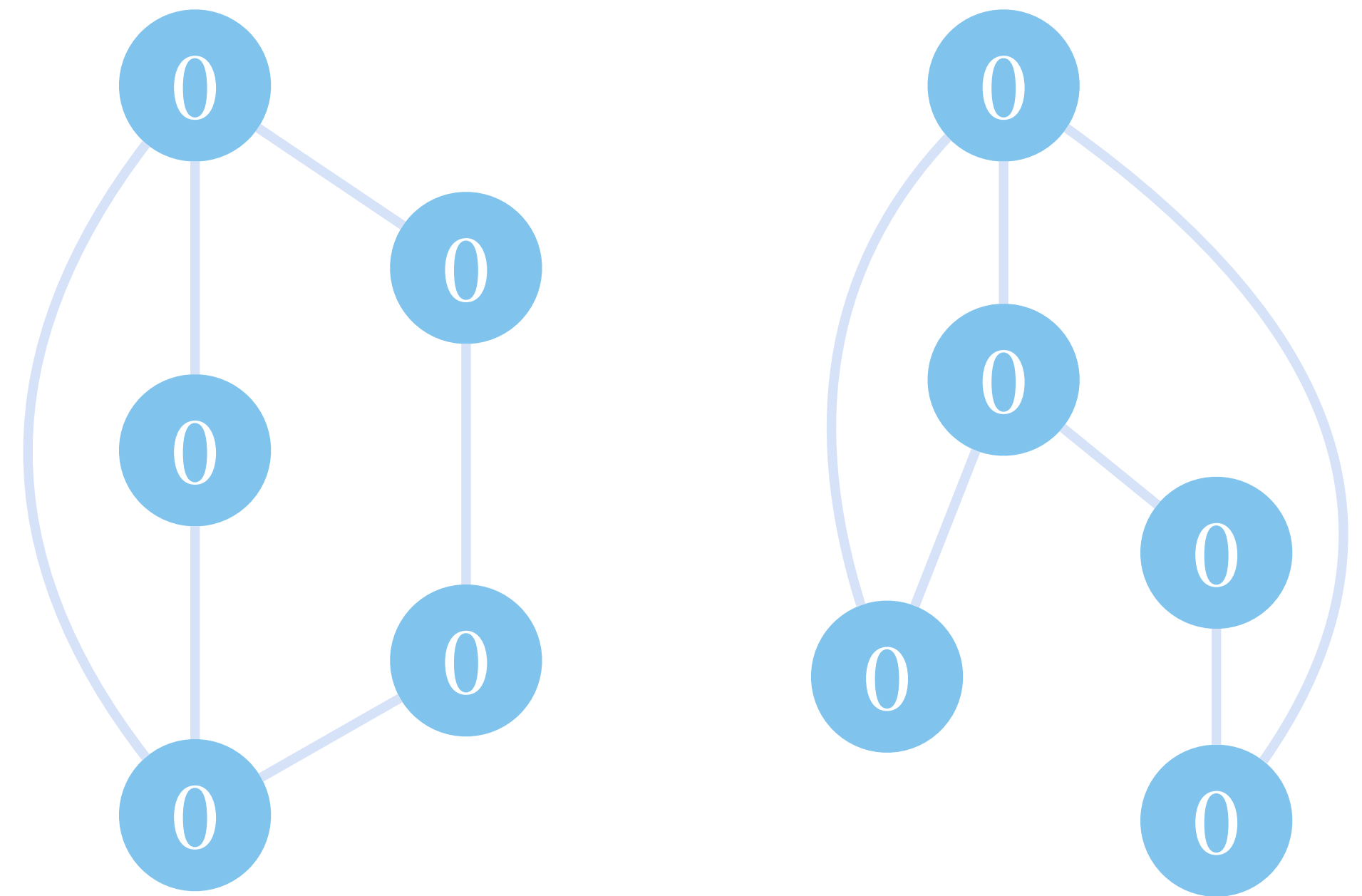
Figure 5: The Weisfeiler-Lehman Isomorphism Algorithm

# WL Isomorphism Test

Algorithm<sup>[3]</sup>

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- Initialization: Set node features  $x_v^0$  to original graph labels



Graph 1

Graph 2

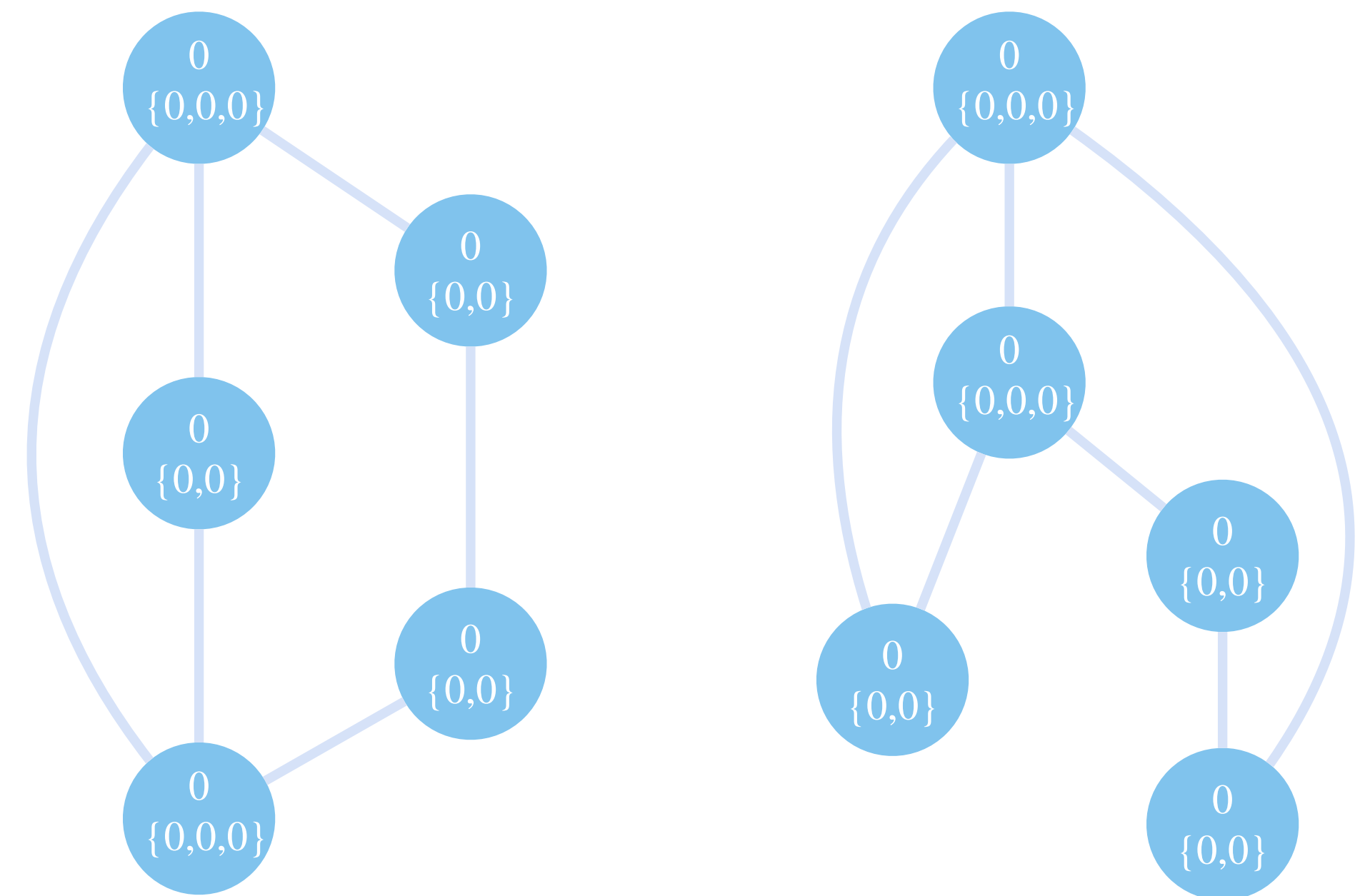
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# WL Isomorphism Test

Algorithm<sup>[3]</sup>

- Initialization: Set node features  $x_v^0$  to original graph labels
- For  $t = 0, \dots, n - 1$ , repeat
  - For each node  $v$  form a multi set  $S_v^t$  of the labels of all neighbors

$$S_v^t = \{x_u^t \mid u \in \mathcal{N}(v)\}$$



Graph 1

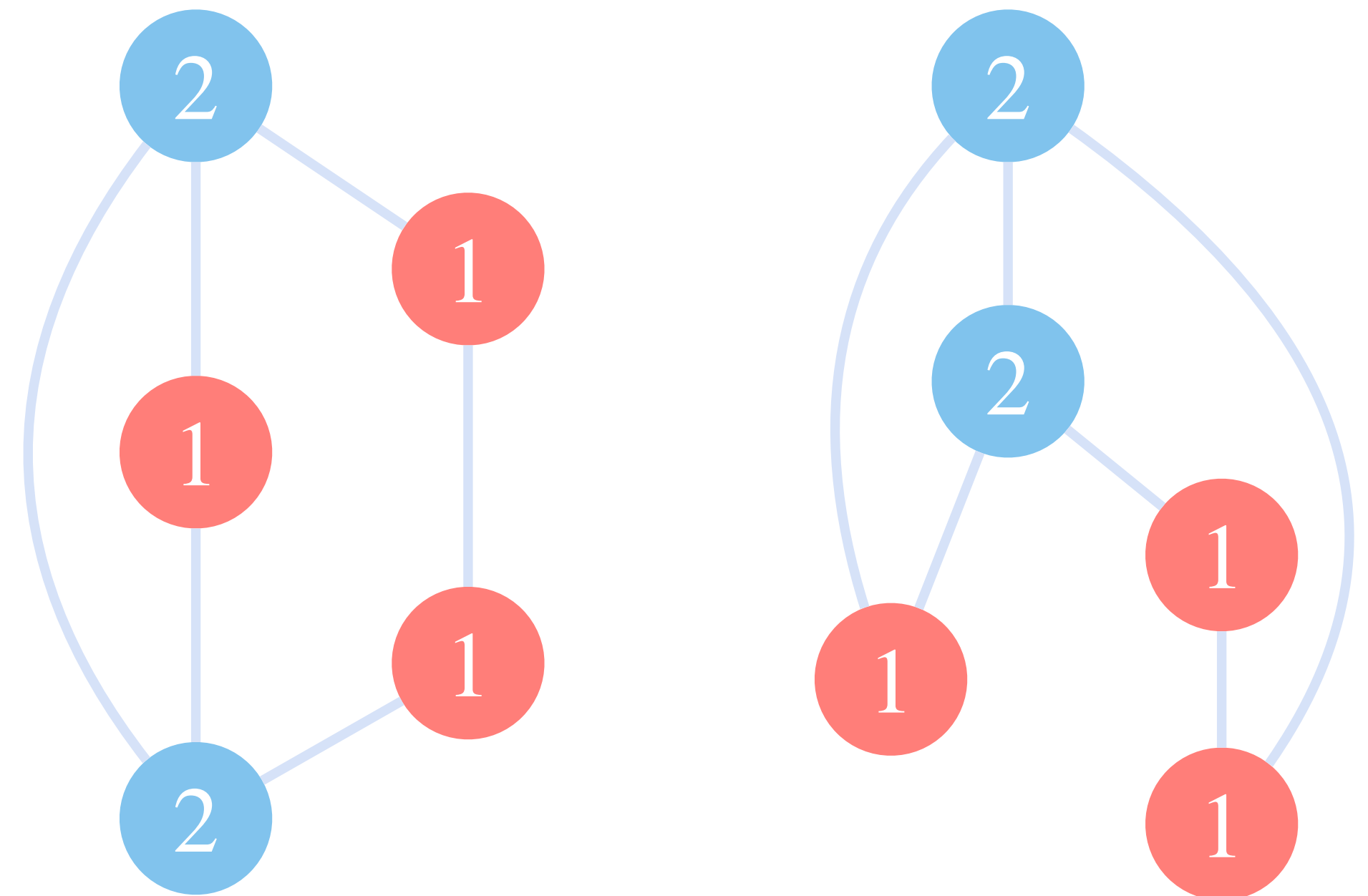
Graph 2

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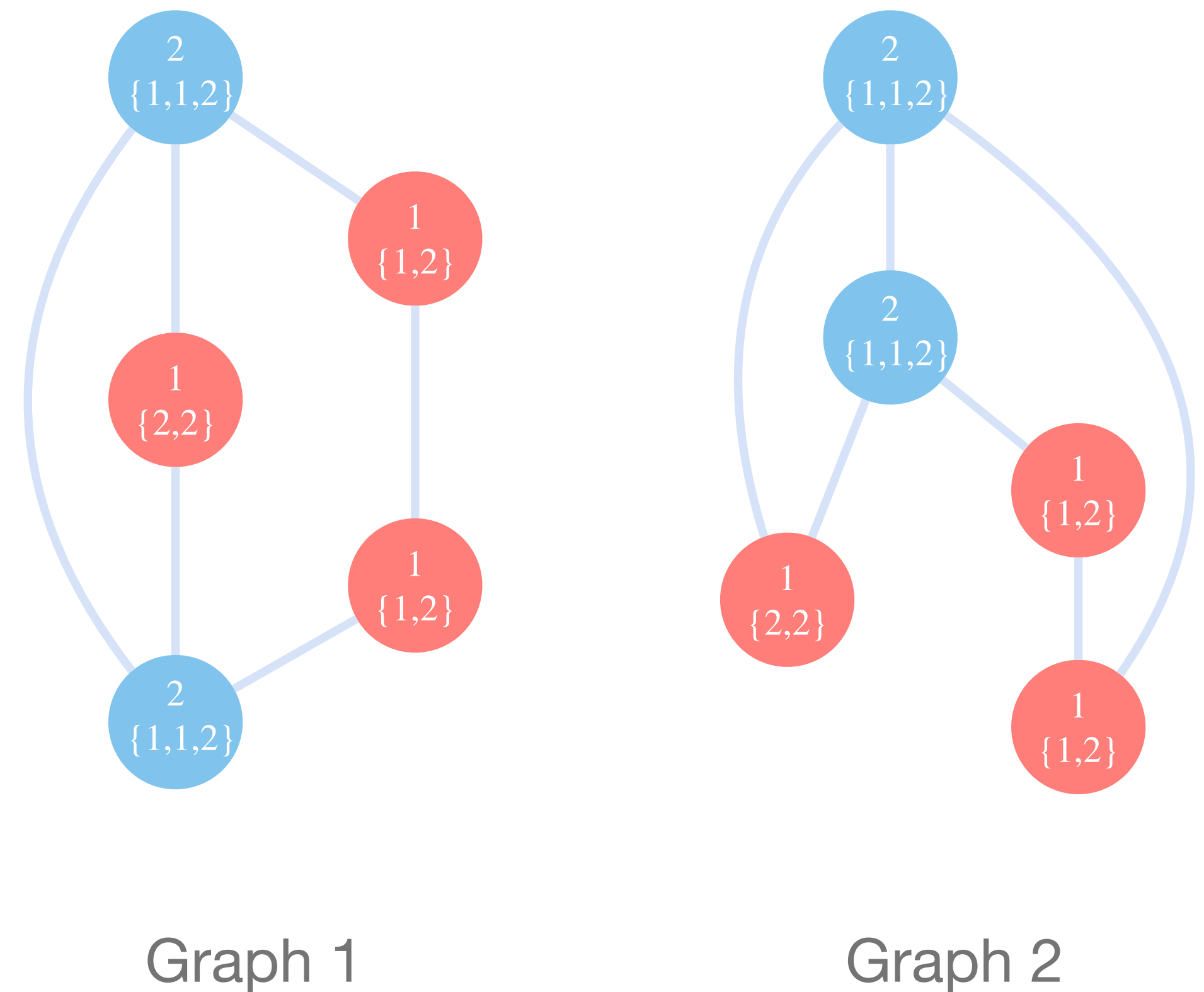
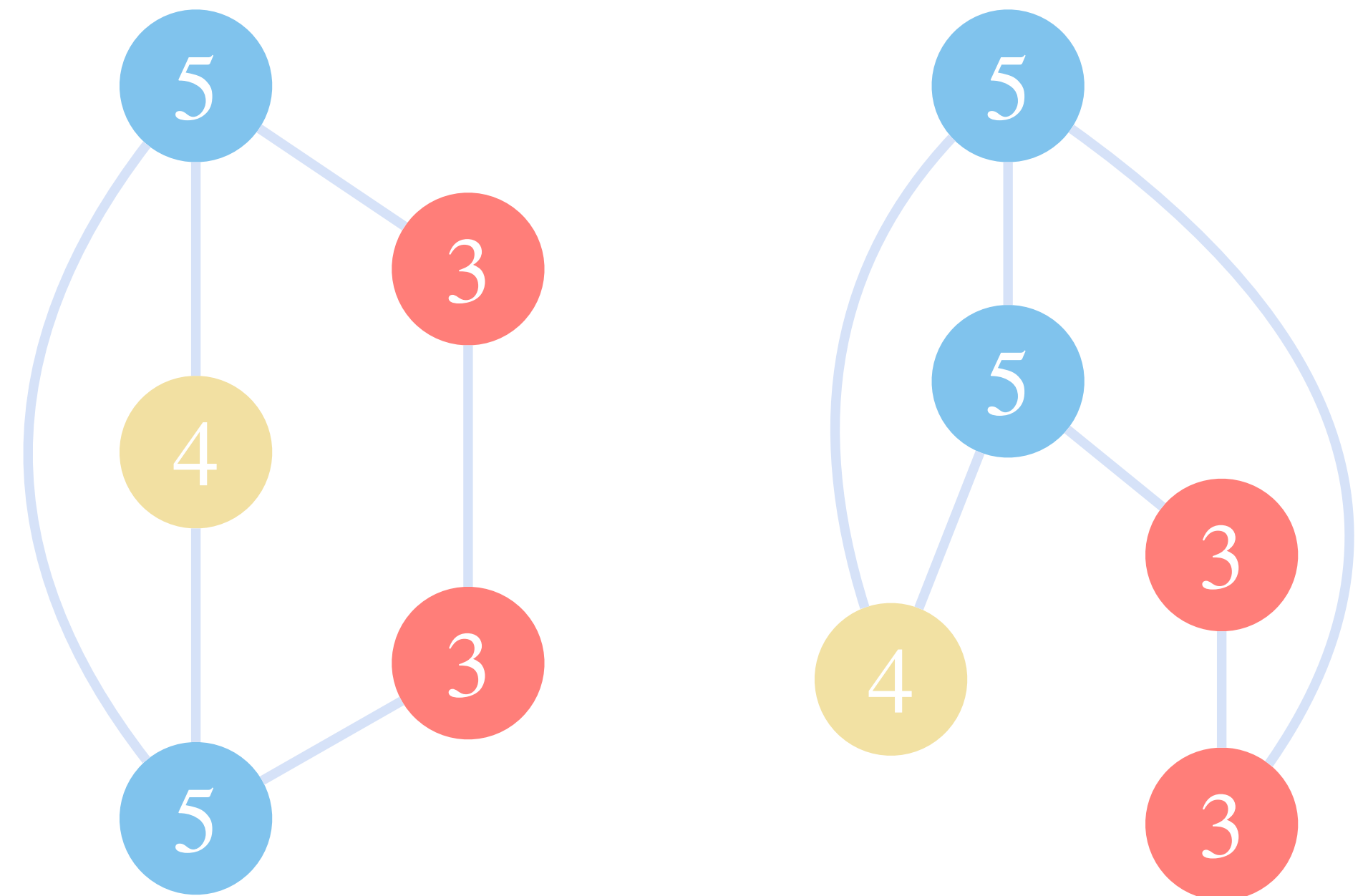


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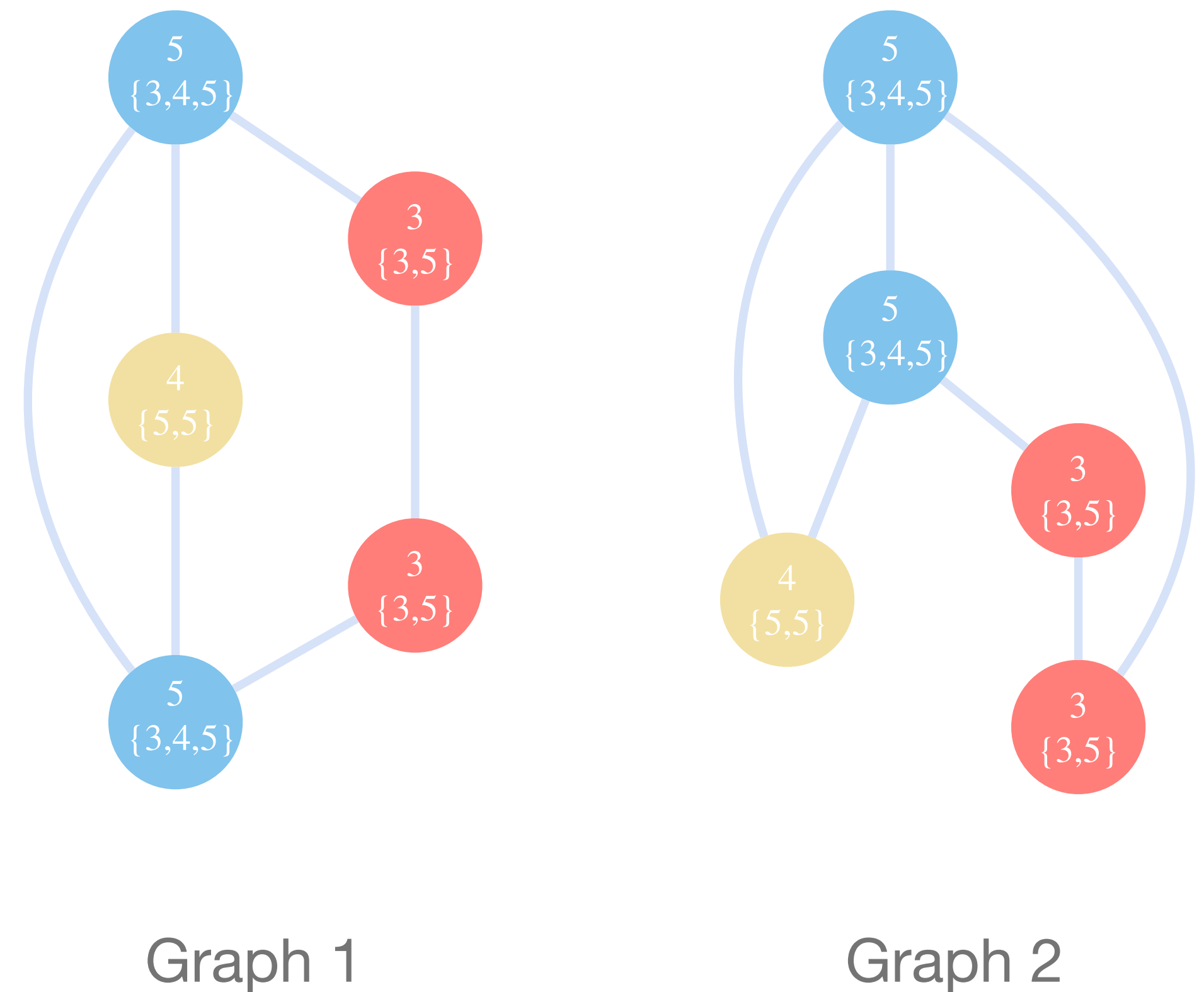


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  - Terminate if assignments of nodes to labels did not change from previous iteration

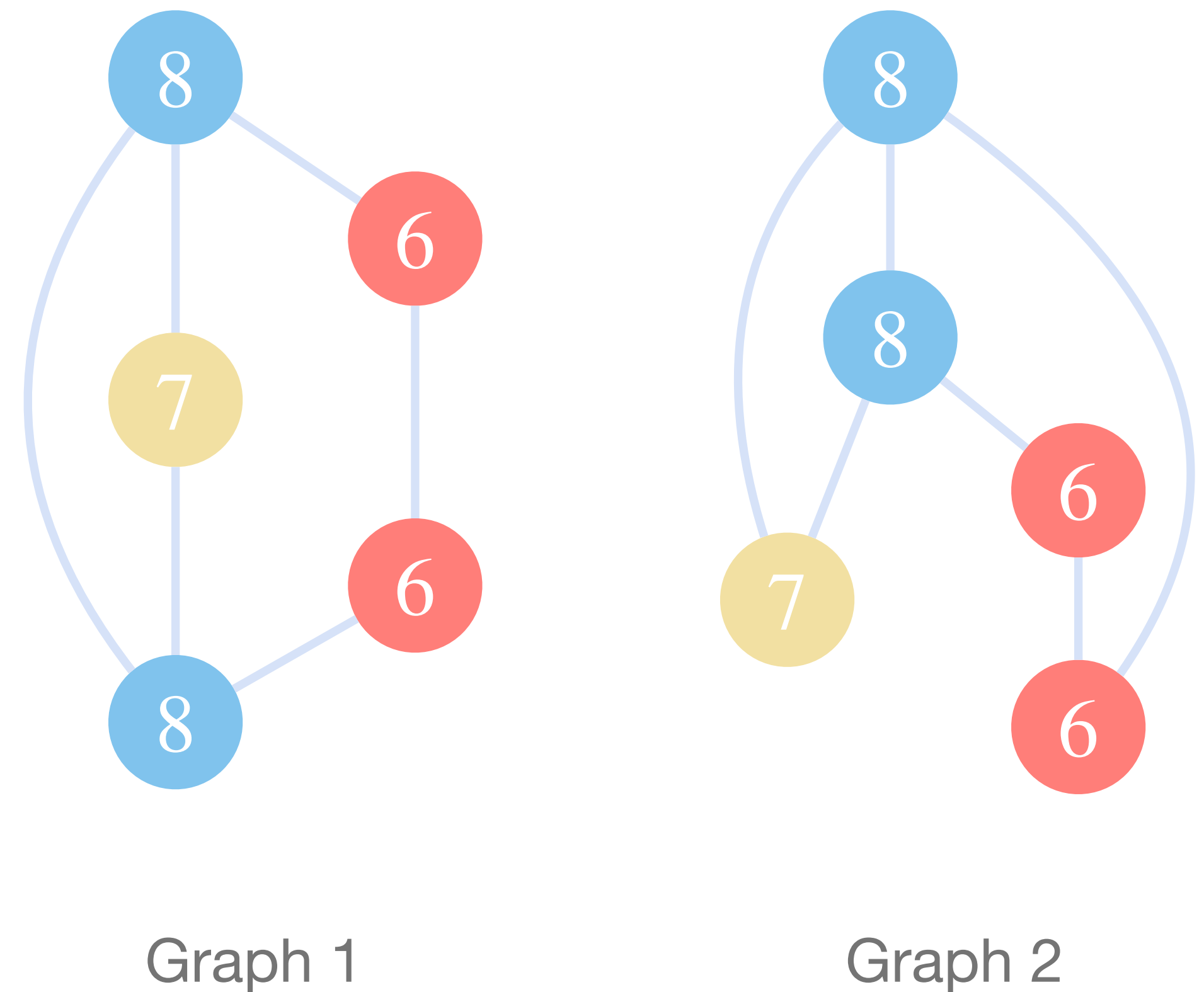
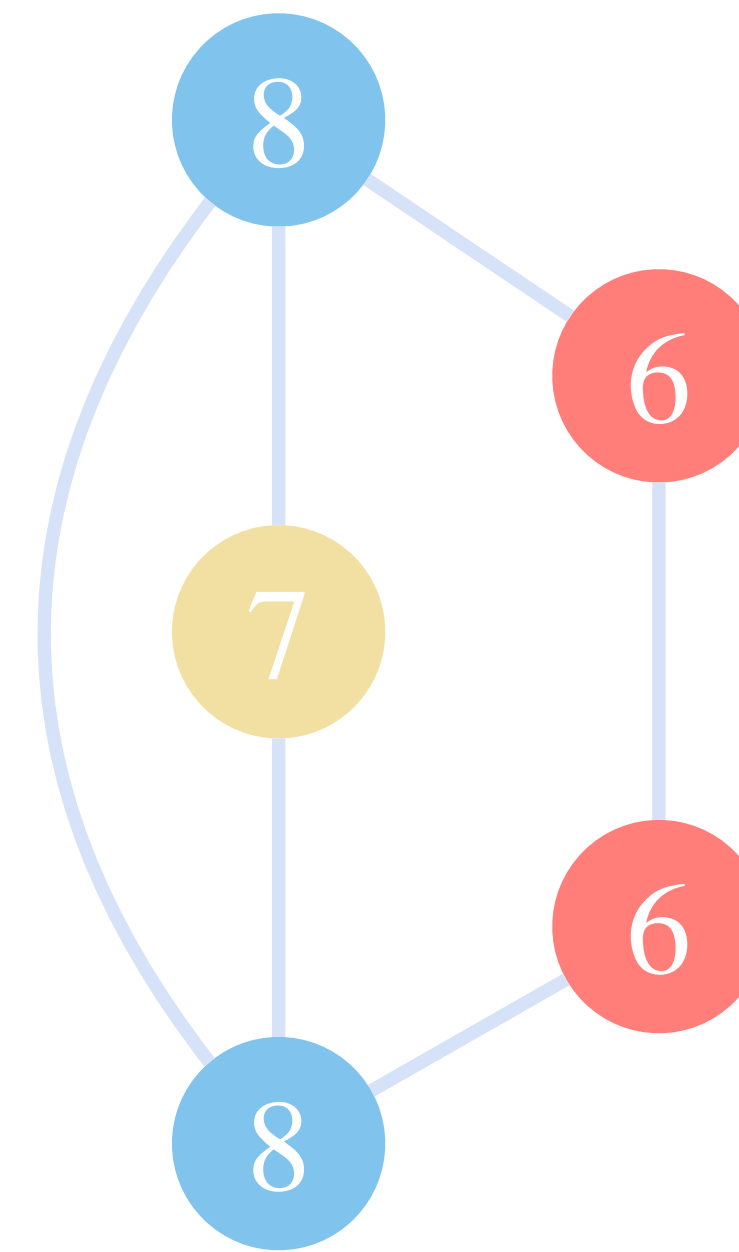


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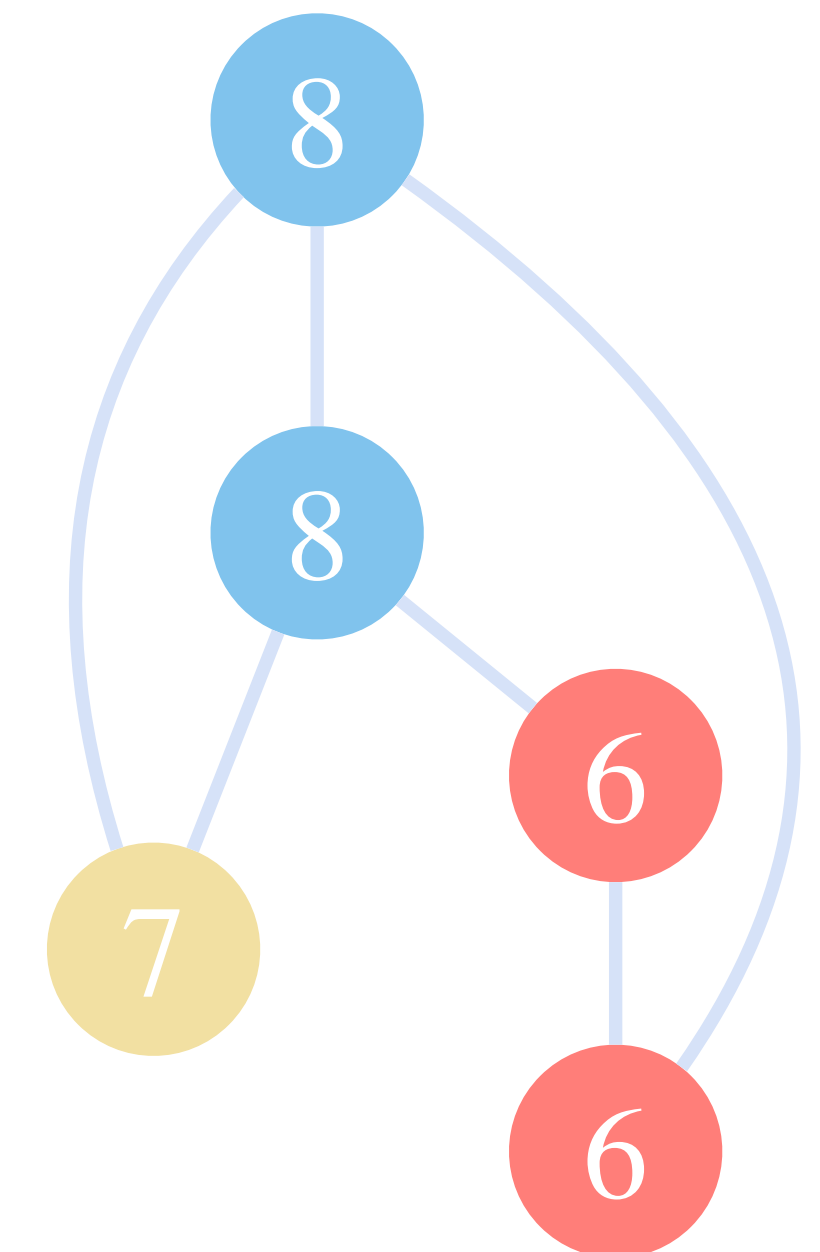
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Graph 1

{6,6,7,8,8}



Graph 2

{6,6,7,8,8}

# WL Isomorphism Test

Connection to GNNs

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- Power of multi set function used in every layer of anonymous GNNs determines power in classifying graph isomorphism

## Theorem 1

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Every GNN is at most as powerful as the WL isomorphism test.<sup>[1]</sup>

## Theorem 2

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A GNN is as powerful as the WL isomorphism test if its layer aggregate, combine and readout functions are injective.<sup>[1]</sup>

# GIN Model

Definition<sup>[1]</sup>

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- GNN model that is as powerful as the WL isomorphism test
- Node update in each layer defined via

$$x_v^k = MLP^k \left( (1 + \epsilon^k) x_v^{k-1} + \sum_{u \in \mathcal{N}(v)} x_u^{k-1} \right)$$

where  $\epsilon^k$  are learnable parameters and  $MLP^k$  are learnable multi layer perceptrons

# GIN Model

## Results

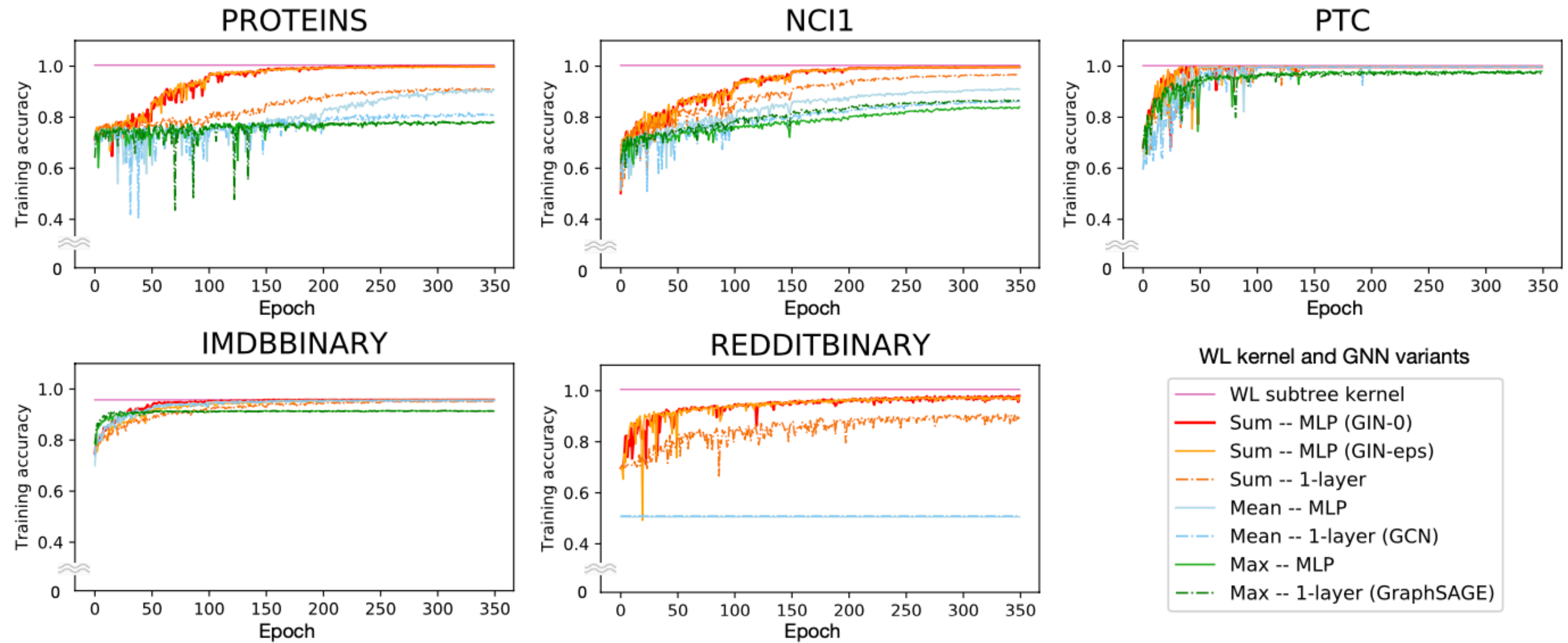


Figure 6: Performance of different GNN models on a selection of graph classification tasks<sup>[1]</sup>

# Less Powerful Models

One-layer perceptron<sup>[1]</sup>

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## Lemma

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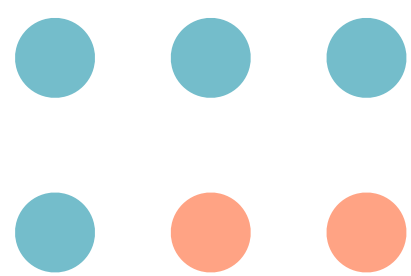
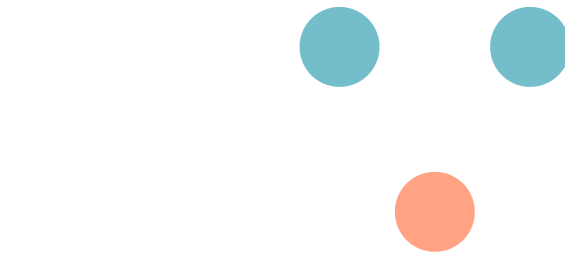

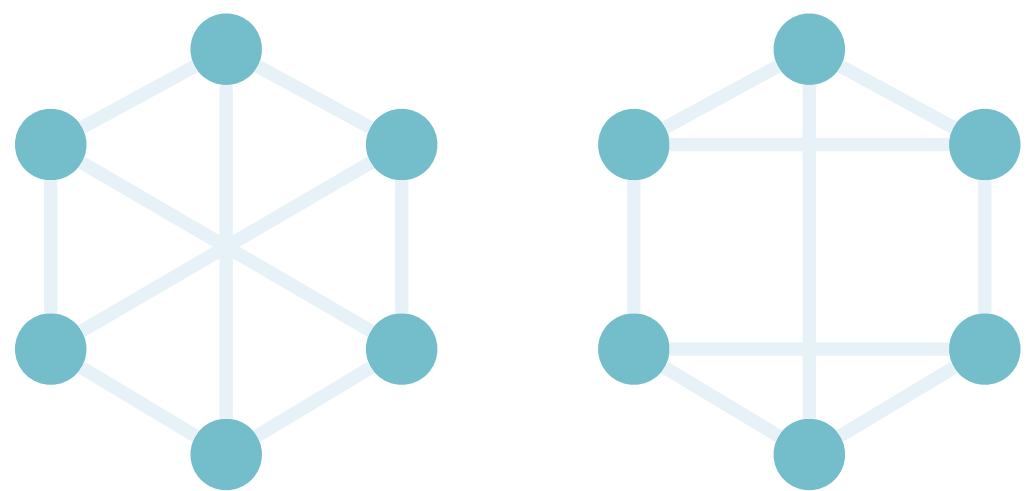
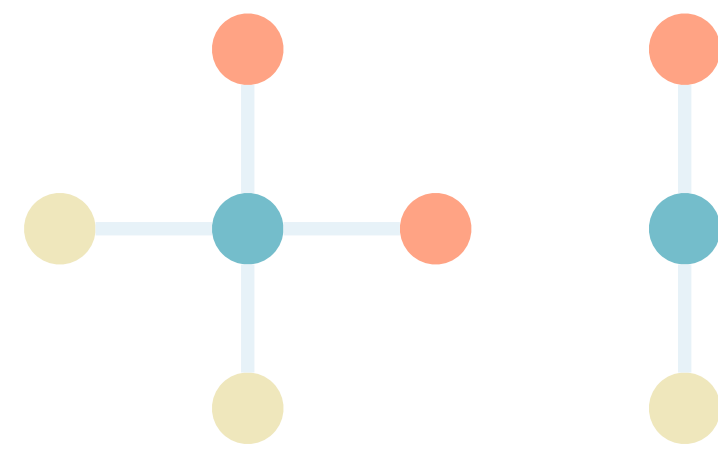
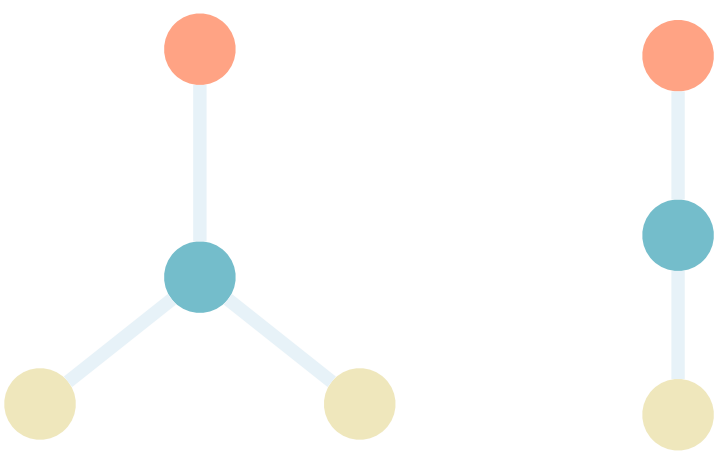
There exist finite multi sets  $X_1 \neq X_2$ , such that for any linear mapping  $W$

$$\sum_{x \in X_1} \text{ReLU}(Wx) = \sum_{x \in X_2} \text{ReLU}(Wx)$$

- Linear model (without bias term) fails to distinguish between some multi sets
- One-layer perceptron is not a universal approximator of multi set functions (unlike MLP)

# Less Powerful Models

Different Aggregation Schemes<sup>[1]</sup>

Aggregation Function	Sum	Mean	Max
Classification level	Multiset	Distribution	Set
Sample Input			
Failure Example			



# GNNs with port numbering

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# Non-anonymous GNNs

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- Anonymous GNNs cannot distinguish between messages from different neighbors and are at most as powerful as the WL-test
- Idea: Assign port numbering to distinguish between different neighbours

# Port Numbering

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## Definition: Port

---

A port of a graph  $G$  is a pair  $(v, i)$  where  $v \in V$  and  $i \in \{1, 2, \dots, \deg(v)\}$ . We denote the set of all ports of  $G$  with  $P(G)$ .

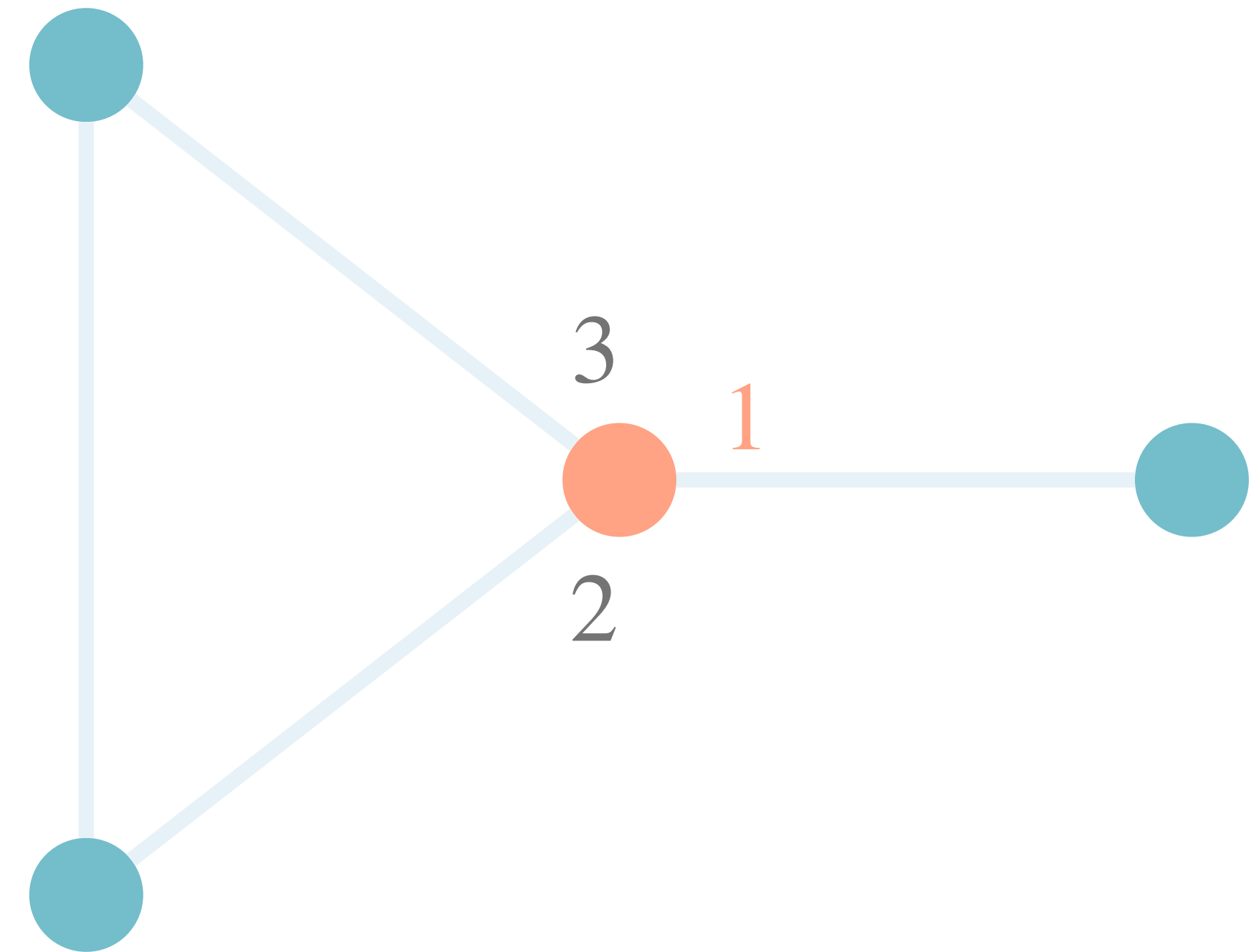


Figure 7: Example of a consistent port numbering<sup>[4]</sup>

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## Definition: Port Numbering

---

A port numbering is a function  $p : P(G) \rightarrow P(G)$ , such that for any edge  $(u, v)$ , there exist  $i, j$  with  $p(u, i) = (v, j)$ .

We call  $p$  consistent if it is self-inverse, i.e.  $p(p(v, i)) = (v, i)$ .

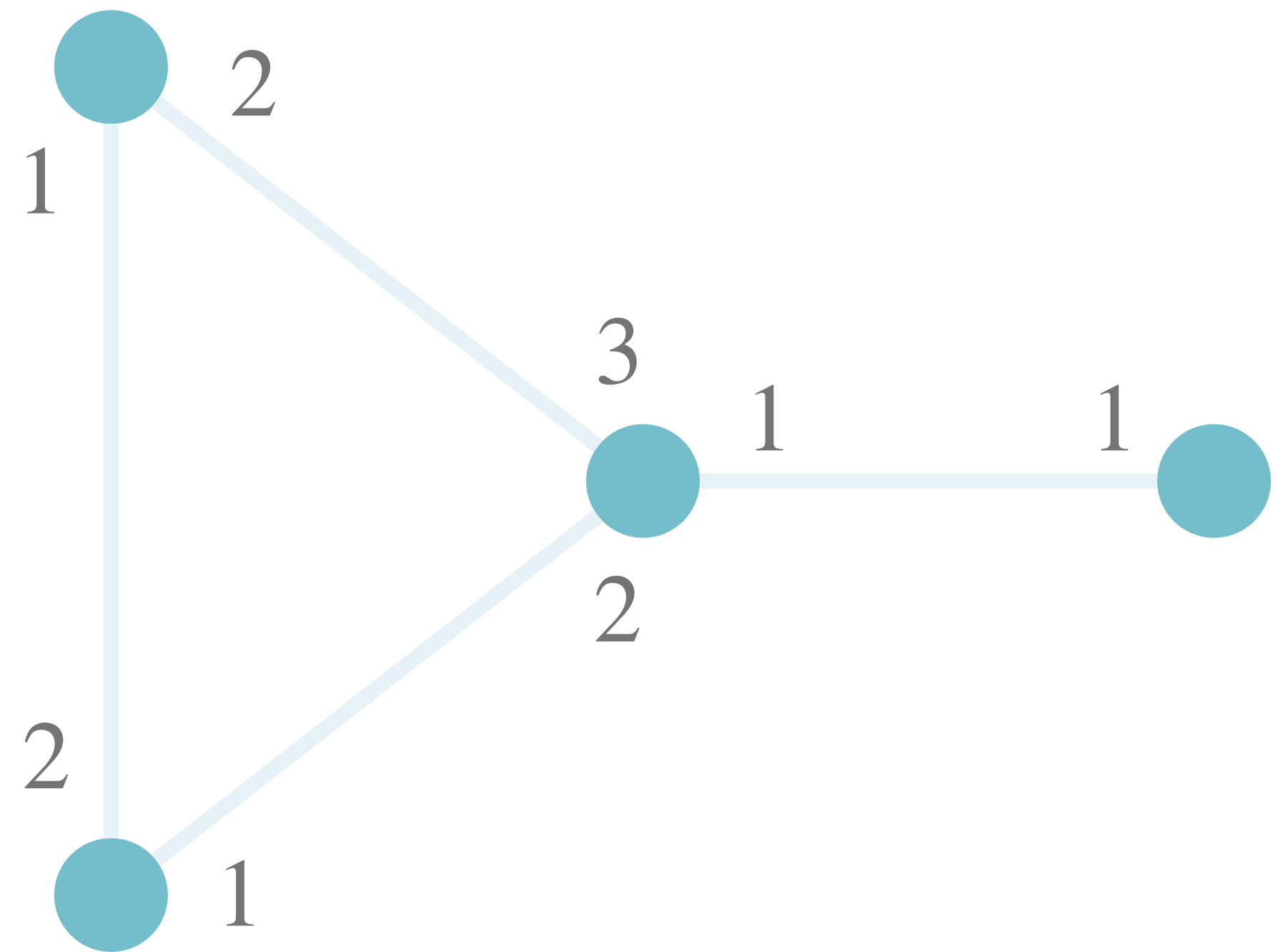


Figure 7: Example of a consistent port numbering<sup>[4]</sup>

# Vector-vector consistent GNNs

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- Let  $p$  be a consistent port numbering and denote its two components by  $p_1, p_2$ , i.e.

$$p(v, i) = (p_1(v, i), p_2(v, i))$$

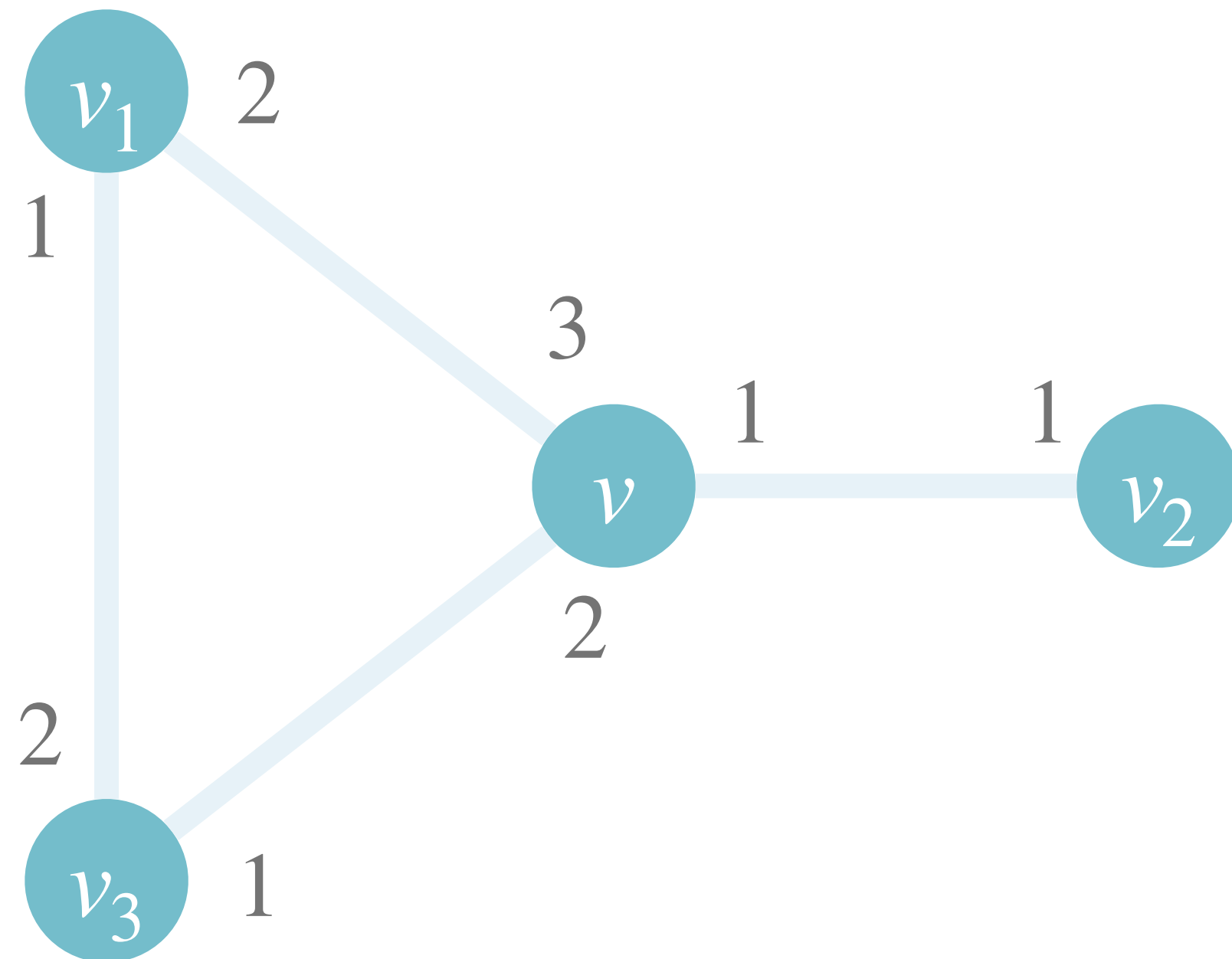
- Extend anonymous GNNs by including consistent port numbering in layer input

$$x_v^{t+1} = f_\theta \left( x_v^t, \left( x_{p_1(v,1)}^t, p_2(v,1) \right), \left( x_{p_1(v,1)}^t, p_2(v,1) \right), \dots, \left( x_{p_1(v,\Delta)}^t, p_2(v, \Delta) \right) \right)$$

- Port numbering can be computed beforehand in linear time

# Vector-vector consistent GNNs

Example



$$p(v,1) = (v_2,1)$$

$$p(v,2) = (v_3,1)$$

$$p(v,3) = (v_1,2)$$

$$\begin{aligned} x_v^{t+1} &= f_\theta \left( x_v^t, \left( x_{p_1(v,1)}^t, p_2(v,1) \right), \left( x_{p_1(v,1)}^t, p_2(v,1) \right), \dots, \left( x_{p_1(v,\Delta)}^t, p_2(v, \Delta) \right) \right) \\ &= f_\theta \left( x_v^t, \left( x_{v_2}^t, 1 \right), \left( x_{v_3}^t, 1 \right), \left( x_{v_1}^t, 2 \right) \right) \end{aligned}$$

# Vector-vector consistent GNNs

CPNGNNs

---

- Authors of [3] introduce Consistent Port Numbering Graph Neural Networks (CPNGNNS)

$$x_v^{t+1} = \text{ReLU} \left( W^t \cdot \text{CONCAT} \left( x_v^t, x_{p_1(v,1)}^t, p_2(v,1), x_{p_1(v,1)}^t, p_2(v,1), \dots, x_{p_1(v,\Delta)}^t, p_2(v, \Delta) \right) \right)$$

$$x_v^{final} = \text{MLP} (x_v^T) \quad (\text{in final layer})$$

- CPNGNNs (and VVC-GNNs) are strictly more powerful than regular GNNs
- Example: Finding single leaf problem

# Vector-vector consistent GNNs

CPNGNNs

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# Vector-vector consistent GNNs

Single Leaf Problem<sup>[4]</sup>

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- Input: star graph
- Output: A single marked leaf node
- Basic GNNs fail since different leaf nodes cannot be distinguished and output coincides

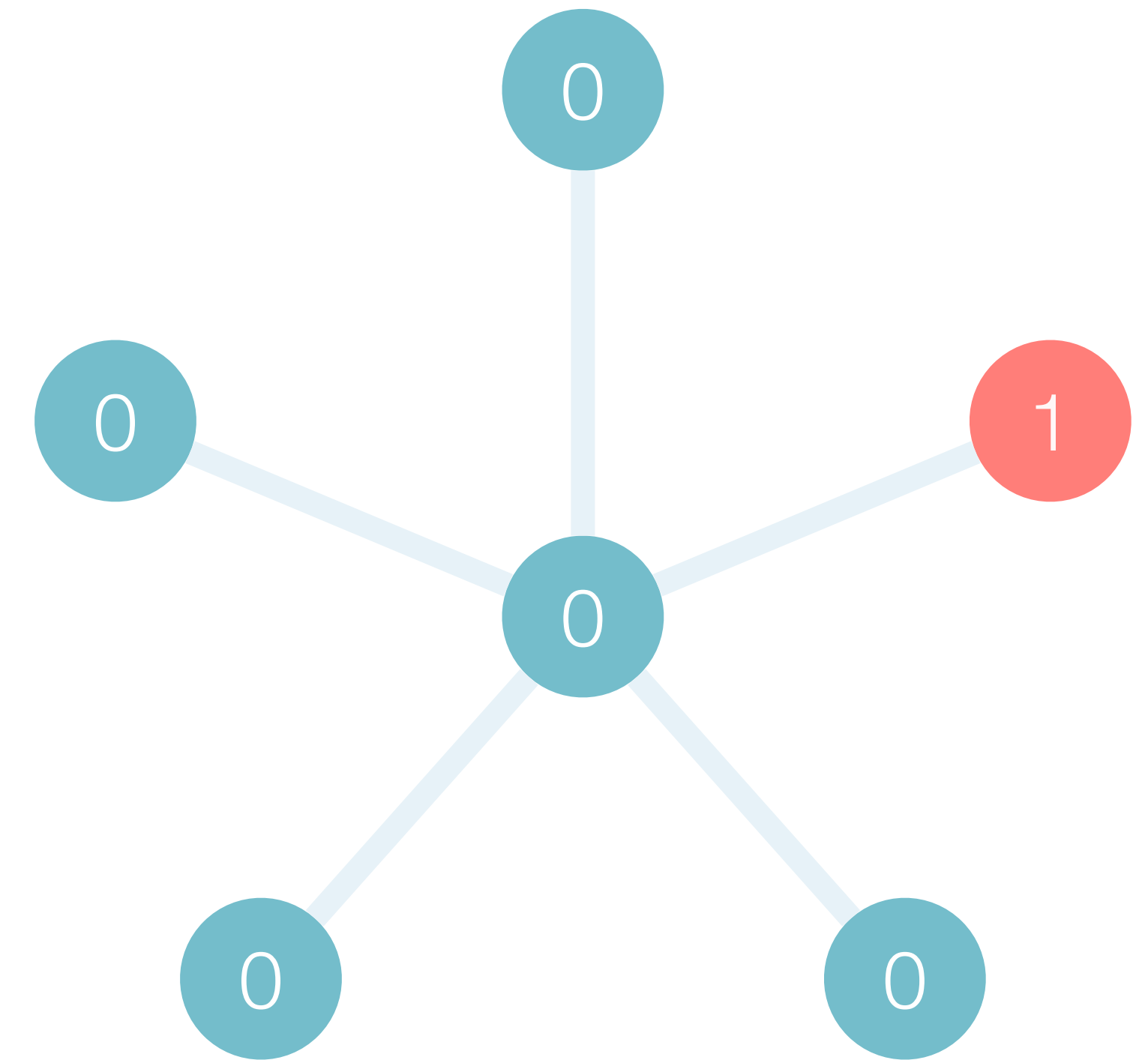


Figure 8: Example instance of single leaf problem

# Distributed Computing

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# GNNs with unique vertex IDs

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- Strictly more powerful than other GNN classes
- Turing universal under certain conditions
- Problems arise during training since GNNs with unique vertex IDs do not generalise well
- Limitations for GNNs with unique vertex IDs also hold for other types of GNNs

# LOCAL and CONGEST

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- Distributed computing models with unique node IDs
1. Communication network
    - Represented by graph  $G$
    - Each node represents a machine and communicates only with its neighbors

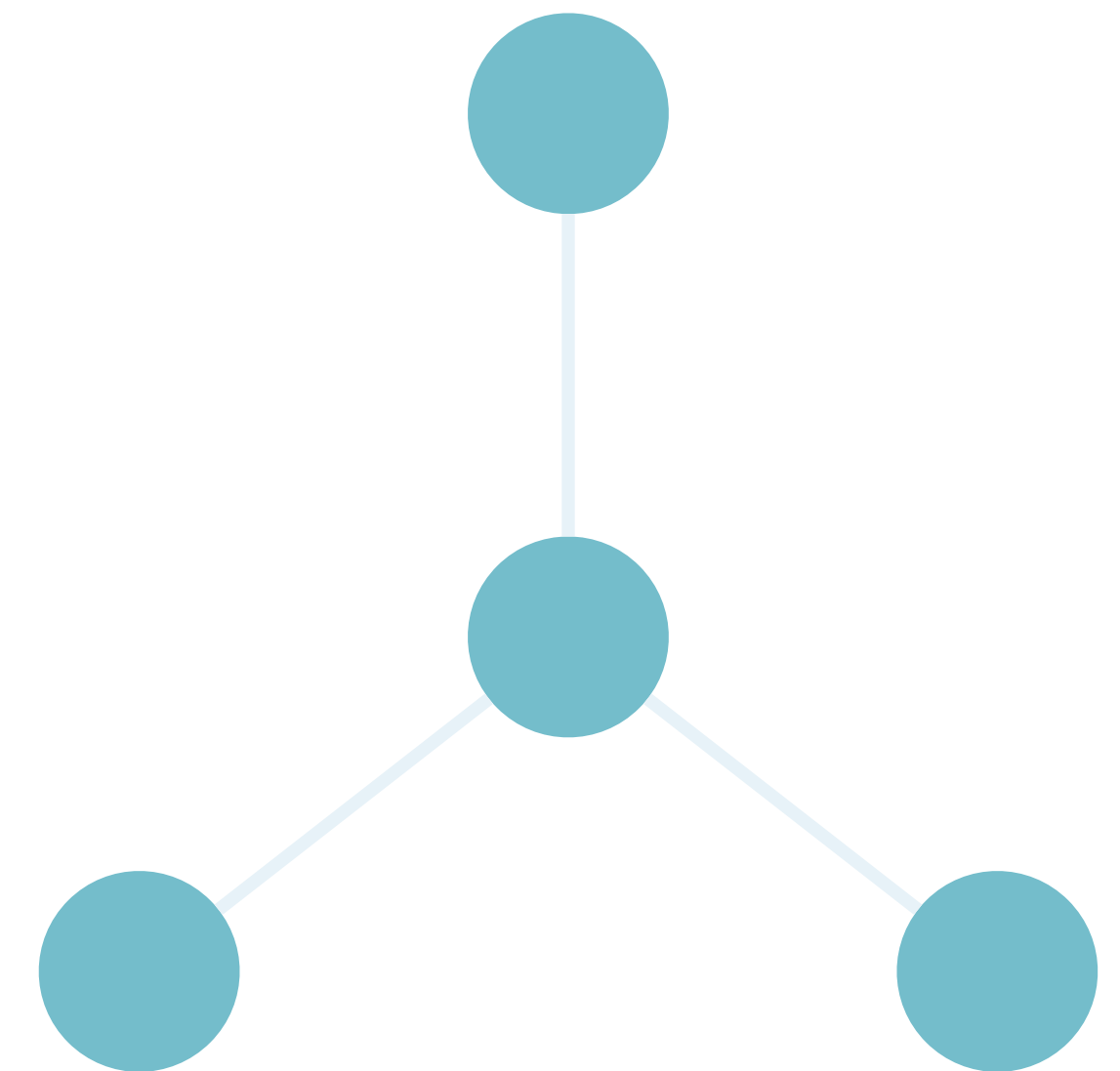


Figure 9: The LOCAL model of computation

# LOCAL and CONGEST

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  2. Synchronous computation
    - Computation performed in synchronous rounds where each round consists of two steps
      - i) Propagate messages between neighbors
      - ii) Perform arbitrarily powerful computation for each node

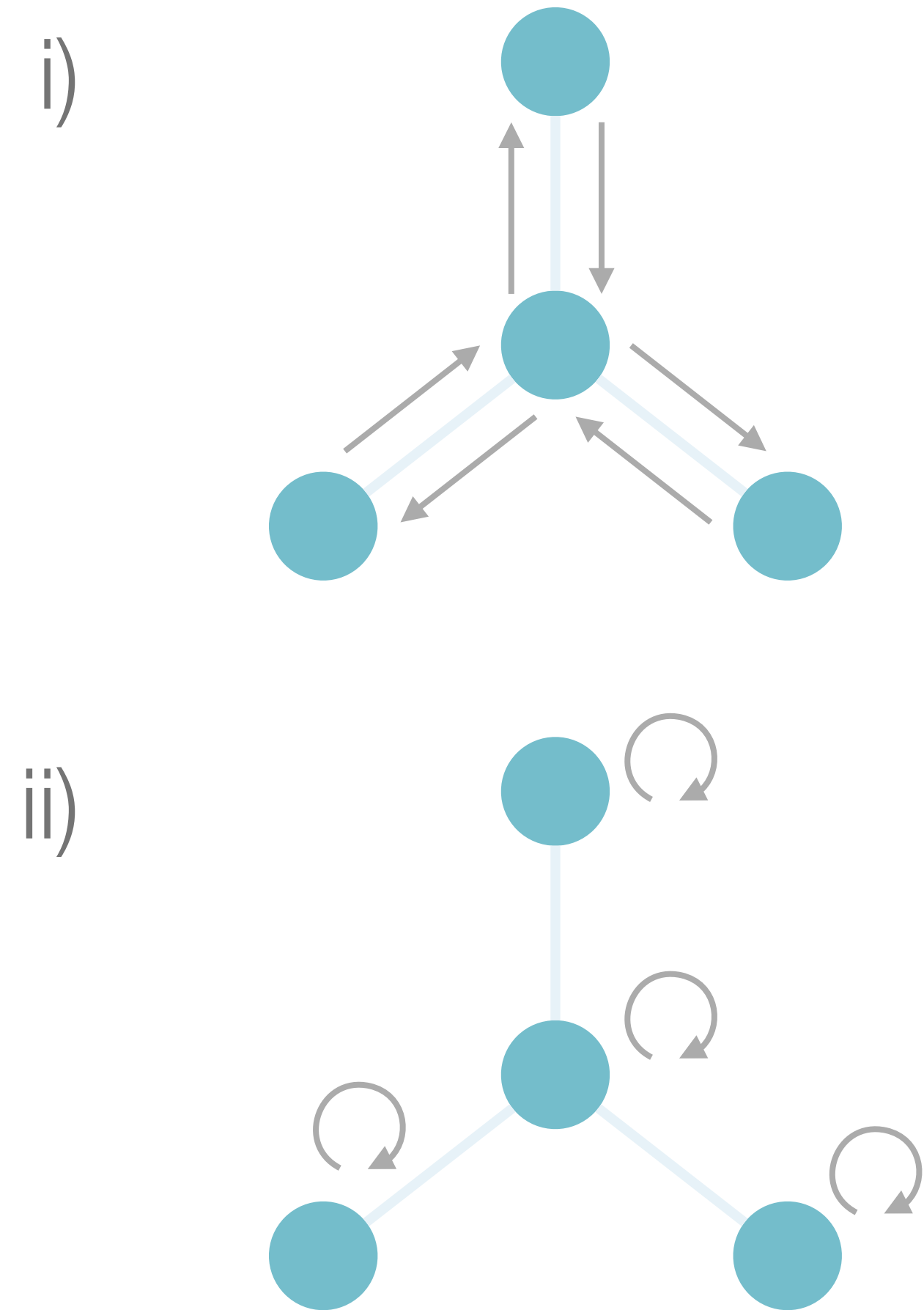


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  3. Message size
    - In CONGEST model: restricted in size to  $b$  bits

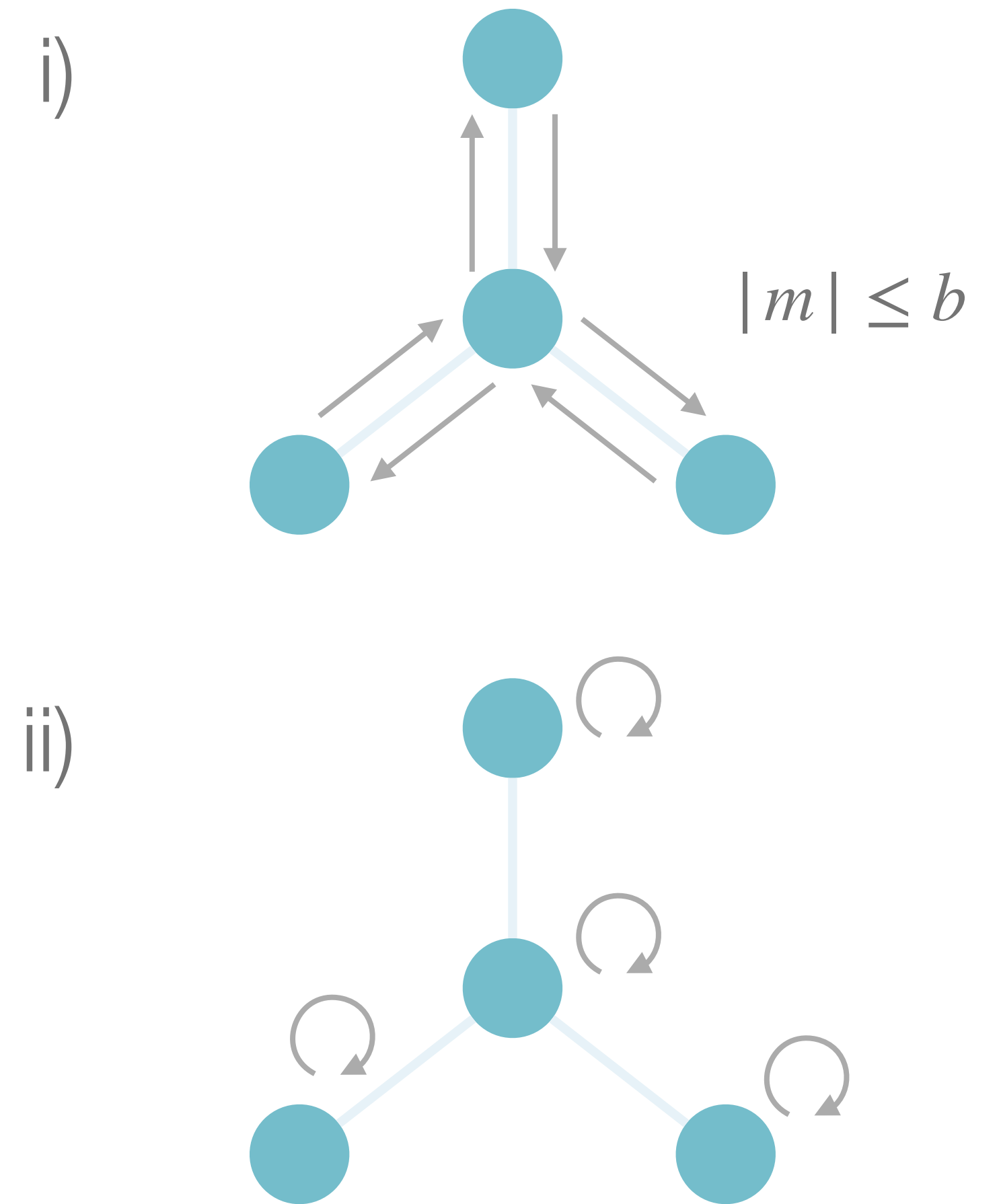


Figure 9: The LOCAL model of computation

# LOCAL and CONGEST

Connection to GNNs

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## Theorem

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Message passing GNNs with unique vertex IDs and Turing complete aggregate and combine functions are equivalent to algorithms in the LOCAL model of computation.<sup>[5]</sup>

- Allows us to infer limits for the computational complexity of GNNs by leveraging results from the LOCAL model
- Similarly, we can infer limits for GNNs with limited width, using results from the CONGEST model

# Requirements for Turing Universality

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Message passing GNNs are Turing universal under the following conditions

- i) Each node is uniquely identified
  - ii) The aggregate and combine functions are Turing complete
  - iii) The depth of the GNN is larger than the diameter of the input graph
  - iv) The width of the GNN is unbounded
- Note that universality in the case of graph level classification is trivial if the *READOUT* function is Turing complete



# Requirements for Turing Universality

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Message passing GNNs are Turing universal under the following conditions

- i) Each node is uniquely identified
  - ii) The aggregate and combine functions are Turing complete
- } Required for equivalence to LOCAL model
- 
- iii) The depth of the GNN is larger than the diameter of the input graph
  - iv) The width of the GNN is unbounded
- } Required for Turing universality in LOCAL model

- Note that universality in the case of graph level classification is trivial if the *READOUT* function is Turing complete

# Limits from CONGEST model

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## Theorem

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If a problem  $P$  cannot be solved in less than  $d$  rounds in *CONGEST* using messages of at most  $b$  bits, then  $P$  cannot be solved by a GNN of depth  $d$  and width  $w = \mathcal{O}(b/\log(n))$ .<sup>[5]</sup>

- Yields limits for the depth and width of a GNN, even for local problems
- Example:  $k$ -cycle classification for  $k \geq 4$  requires depth

$$d = \Omega \left( \sqrt{n} / (w \log n) \right) \quad \text{if } k \text{ even,}$$

$$d = \Omega \left( n / (w \log n) \right) \quad \text{if } k \text{ odd.}$$

# Limits from CONGEST model

Experimental results

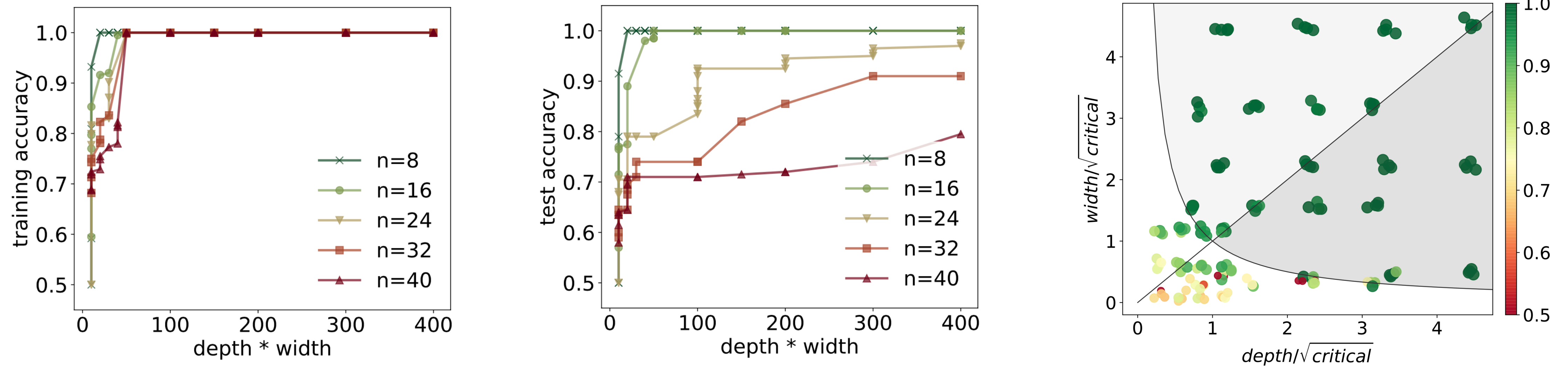


Figure 10: Performance of GNNs with different depth and width on the 4-cycle problem (determining whether a graph contains a 4-cycle).<sup>[5]</sup>

# Communication Capacity and Limitations

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# Communication capacity

- Computational power of GNN dependent on its depth and width: motivates generalising notion of communication complexity
- Assume that each node feature vector takes values in some finite alphabet  $\mathcal{S}$  with  $s = |\mathcal{S}|$  symbols

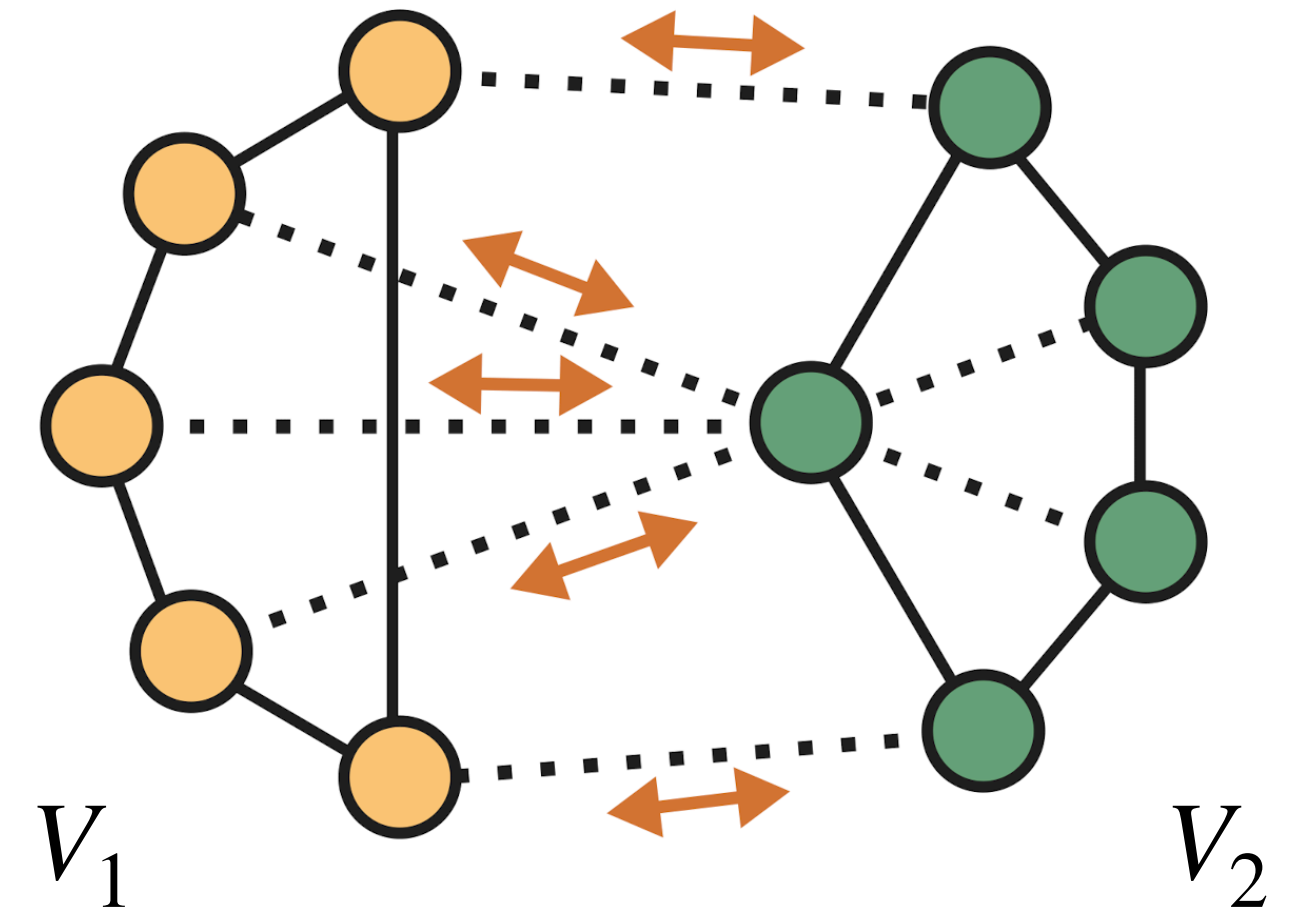


Figure 11: Example of a graph partition

## Definition

Let  $g$  be a GNN and fix a graph  $G = (V, E)$ . For any two disjoint sets  $V_1, V_2 \subseteq V$ , the communication capacity  $c_g$  of  $g$  (with respect to  $G, V_1, V_2$ ) is the maximum number of symbols that can be transmitted from  $V_1$  to  $V_2$  and vice versa.<sup>[6]</sup>

# Communication capacity

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- The communication capacity of a GNN with respect to the partition  $V_1, V_2$  depends on
  - i) Its width  $w$  and its depth  $d$
  - ii) The size of messages passed in each layer
  - iii) The size of its global state (if included)
  - iv) The smallest cut separating the two subsets  $V_1, V_2$

# Communication complexity

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- Two players with respective inputs  $x_a, x_b$  attempt to compute a function  $f(x_a, x_b)$
- A communication protocol  $\pi$  determines the sequence of exchanged symbols between the players
- The number of exchanged symbols is denoted by  $|\pi(x_a, x_b)|$

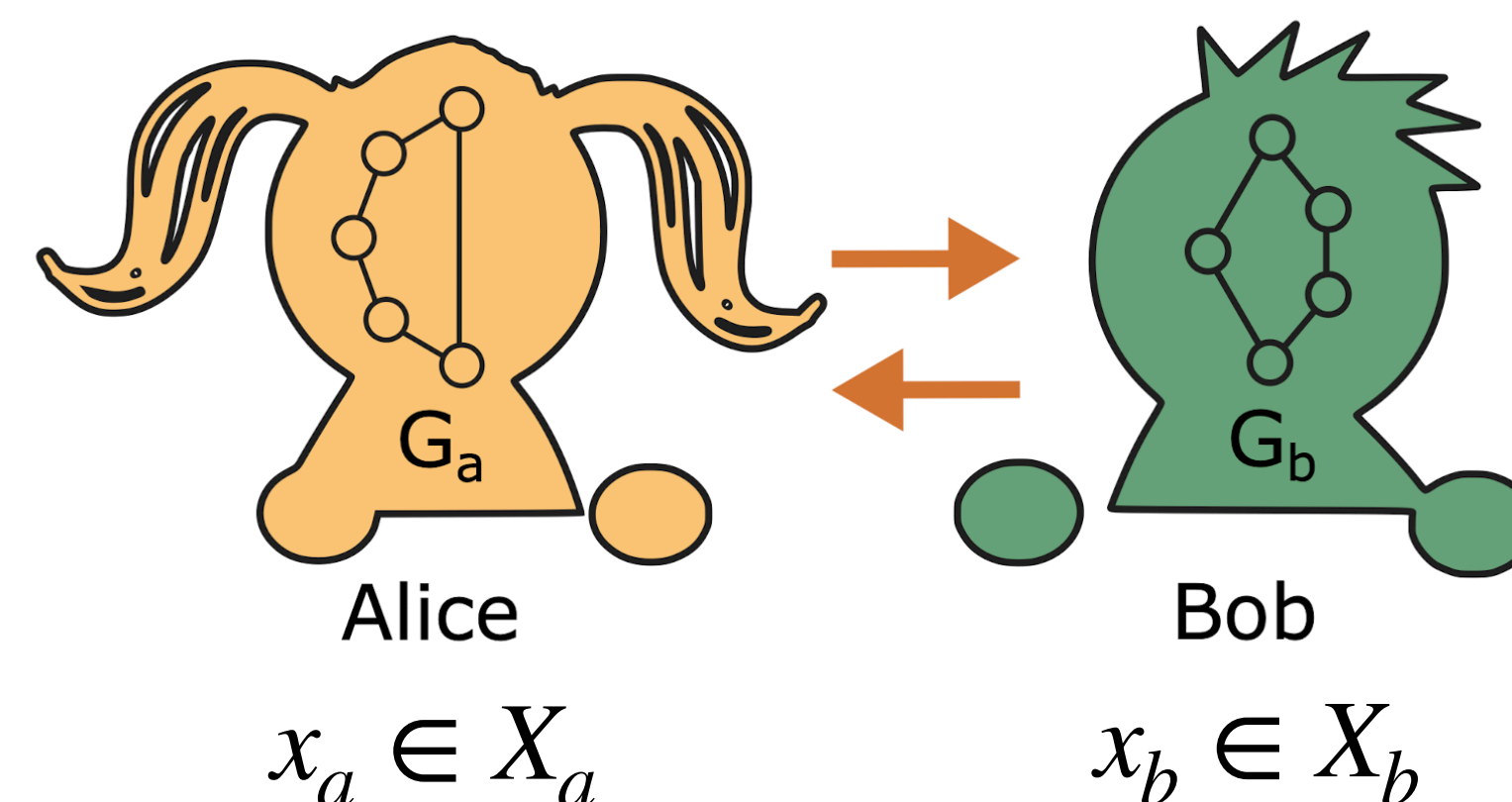


Figure 12: Two players with respective inputs  $x_a, x_b$ , (here depicted as graphs  $G_a, G_b$ )

## Definition

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The communication complexity  $c_f$  of  $f$  corresponds to the minimum worst-case length of any protocol that computes  $f$  [6]

$$c_f = \min_{\pi} \max_{(x_a, x_b) \in X_a \times X_b} |\pi(x_a, x_b)|$$

# Hardness of Graph Isomorphism Problem

- We can relate communication capacity and complexity to derive limitations of GNNs for graph isomorphism
- Idea: Consider two random graphs connected by a small amount of edges
- Results also hold in expectation for these specific sets of graphs

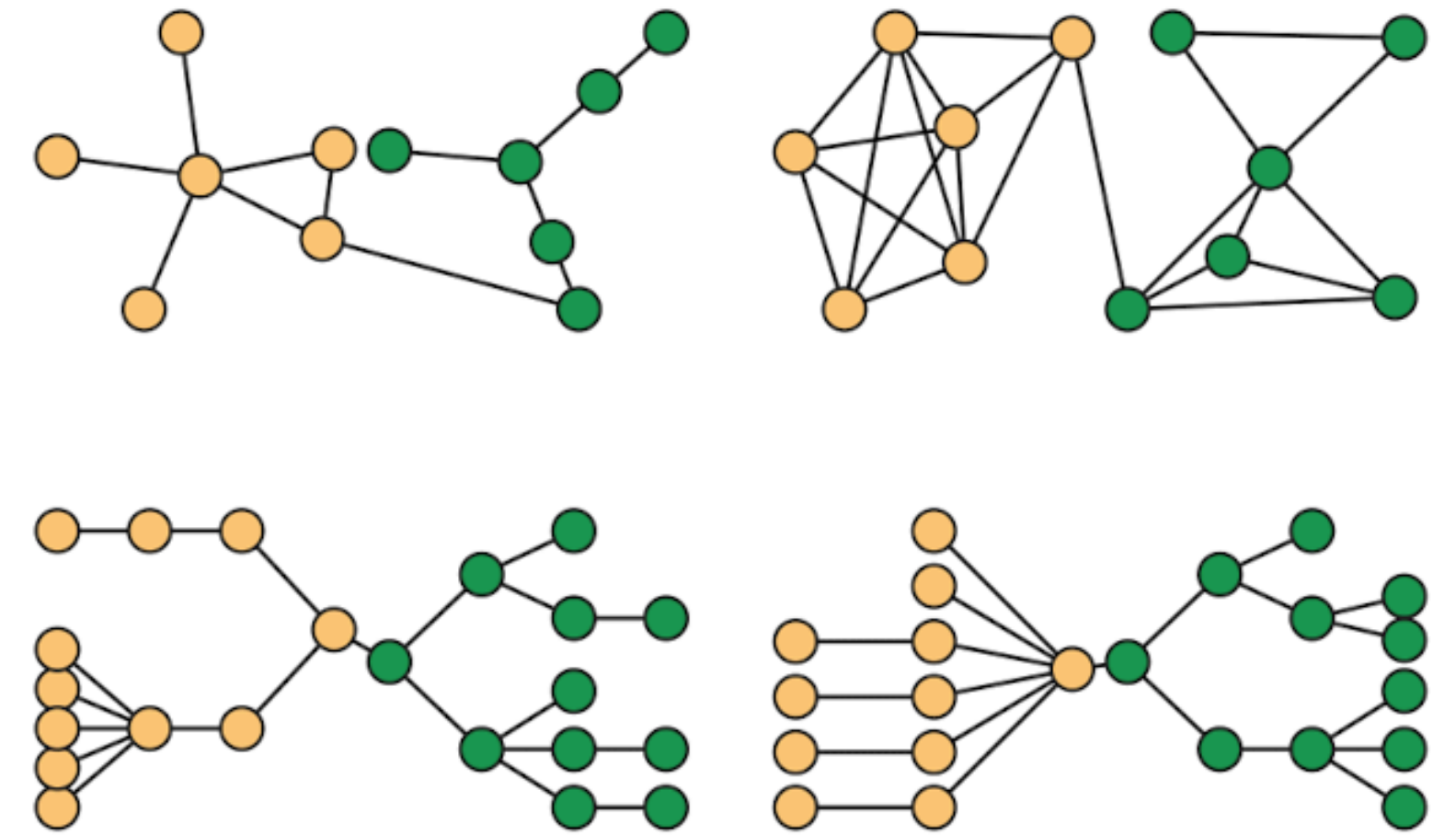


Figure 13: Sample graphs for the hardness proof of graph isomorphism for GNNs

## Theorem

Let  $g$  be a GNN using a majority-voting or consensus based *READOUT* function. To compute the isomorphism class of every graph/tree of  $n$  nodes, it must be that  $c_g = \Omega(n^2)/c_g = \Omega(n)$ .<sup>[6]</sup>



# Hardness of Graph Isomorphism Problem

## Empirical Results

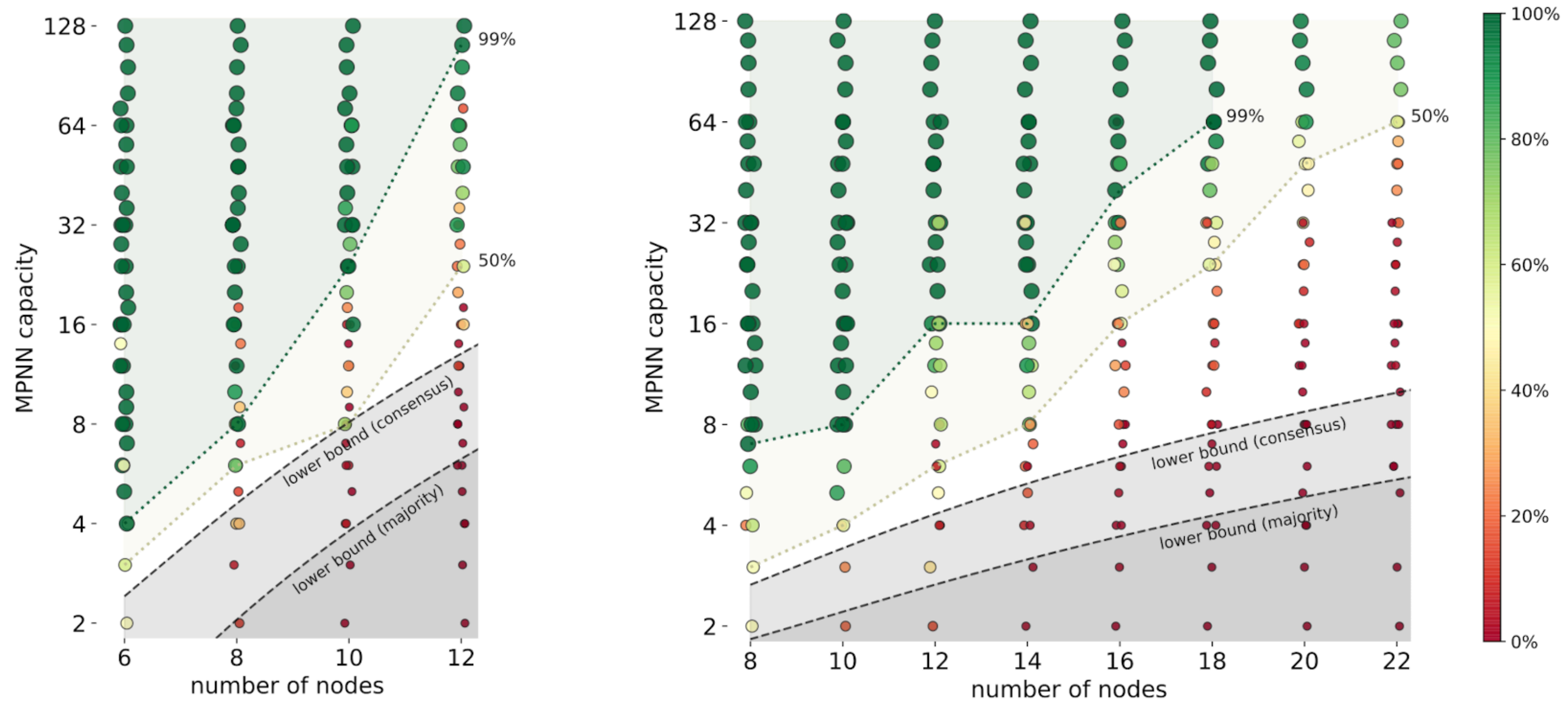


Figure 14: Performance of GNNs with different communication capacity on the graph isomorphism problem for a sample set of general graphs (a) and a set of trees (b)<sup>[6]</sup>.

# Oversquashing

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# Oversquashing

## Definition

The problem radius  $r$  of a graph problem corresponds to its required range of interaction.

- GNN requires at least  $K \geq r$  layers
- Size of receptive field of a node grows exponentially in the number of layers  $K$

$$|\mathcal{N}_v^K| = \mathcal{O}(\exp(K))$$

- For fixed length feature vector  $x_v^t$  this leads to an exponential bottleneck

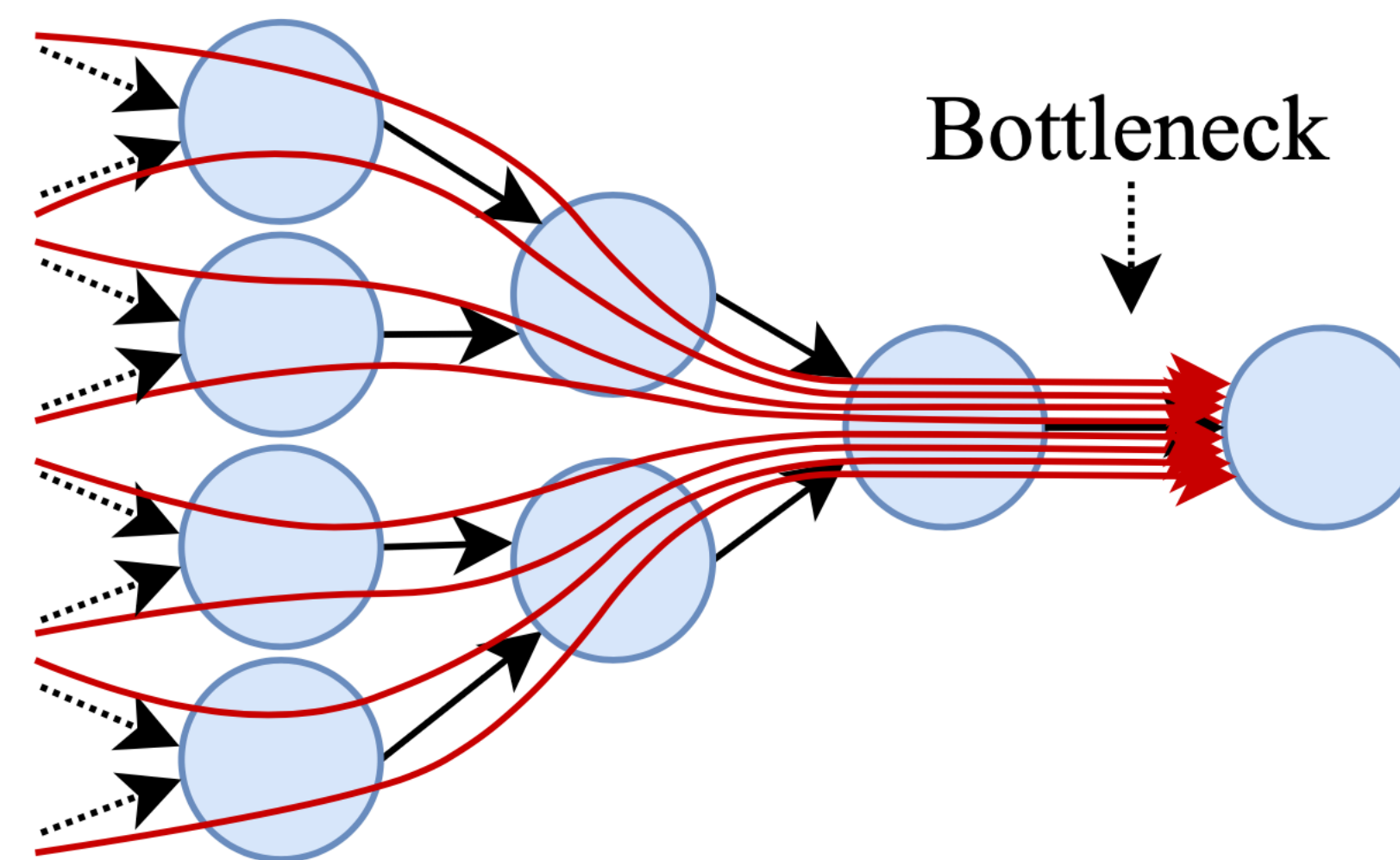


Figure 15: The bottleneck in GNNs with many layers<sup>[7]</sup>

# Oversquashing

## Example Problem

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- In the *NeighborsMatch* problem the goal is to predict the label of a node based on its degree
- Solution requires propagation of information from all labeled nodes to target node
- Leads to bottleneck that prevents fitting the training data perfectly

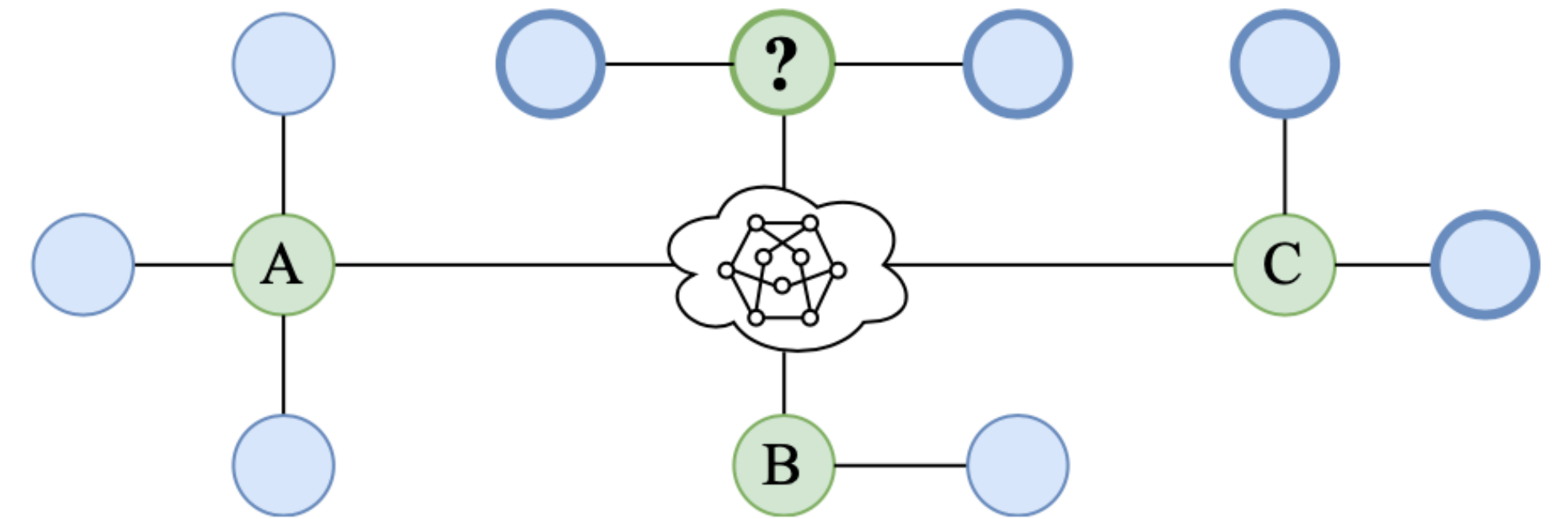


Figure 16: The NeighborsMatch problem. The correct output label for the depicted graph is C.<sup>[7]</sup>

# Oversquashing

## Empirical Results

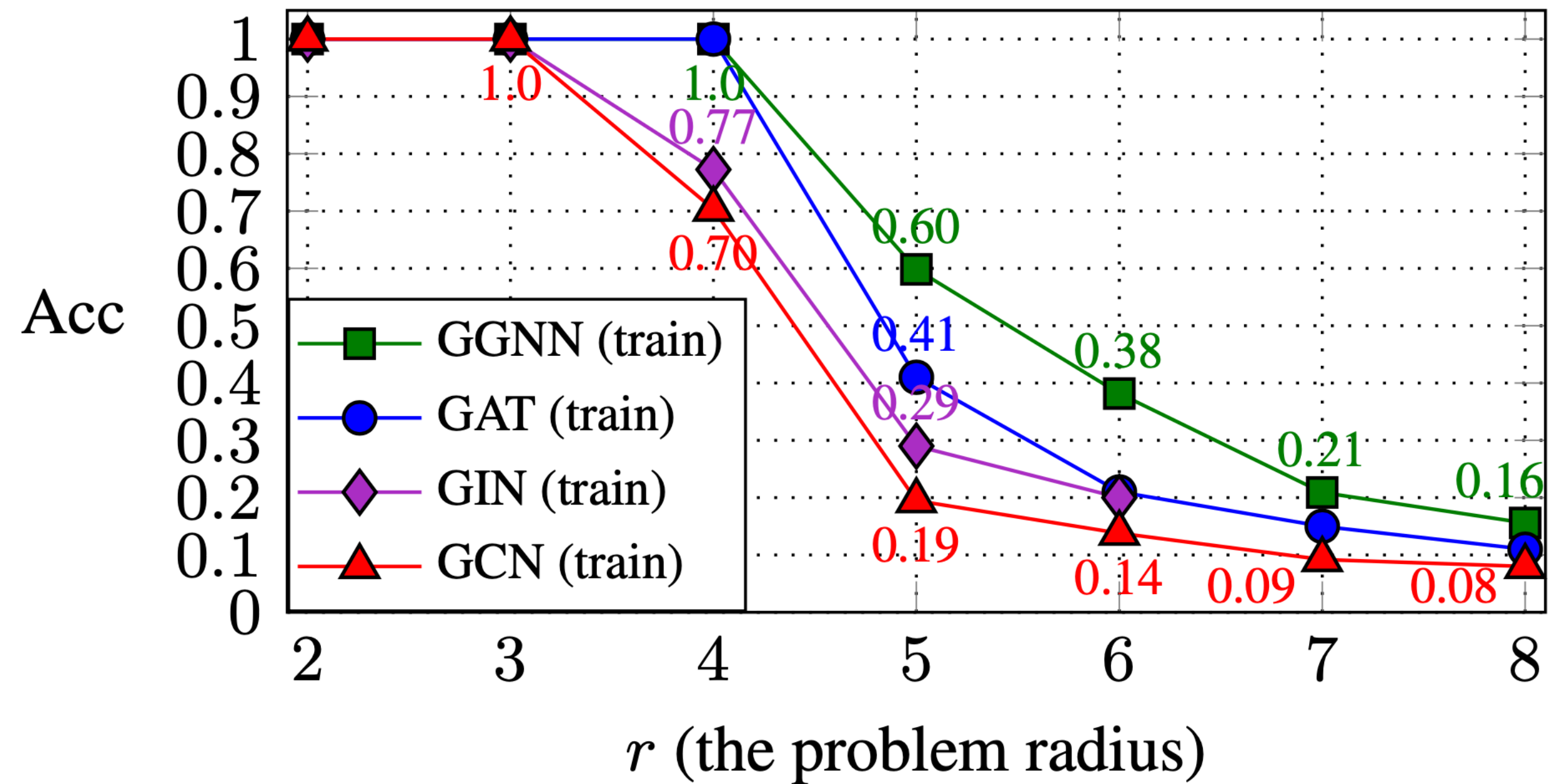


Figure 17: Performance of different GNNs on the NeighborsMatch problem. Underfitting (caused by oversquashing) can be observed from a problem radius of  $r = 4$ .<sup>[7]</sup>

# Conclusion

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# What we covered

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- Hierarchy of different GNN classes
- Anonymous GNNs are (at most) equivalent to the WL isomorphism test w.r.t. graph isomorphism
- Connection between GNNs and models of distributed computation
- Requirements of Turing completeness of GNNs with unique vertex IDs
- Limitations based on depth and width, and, more generally, communication capacity
- The problem of oversquashing in deep GNNs and problems with a large radius

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